

FIG. 1 is a block diagram of a system 10 for simulating a process. The system 10 includes a user interface 12, a modeling and simulation module 14, a data storage and retrieval module 16, a libraries database 18, and a user data files database 20. The user interface 12 is connected to the modeling and simulation module 14. The modeling and simulation module 14 is connected to the data storage and retrieval module 16. The data storage and retrieval module 16 is connected to the libraries database 18 and the user data files database 20.

19

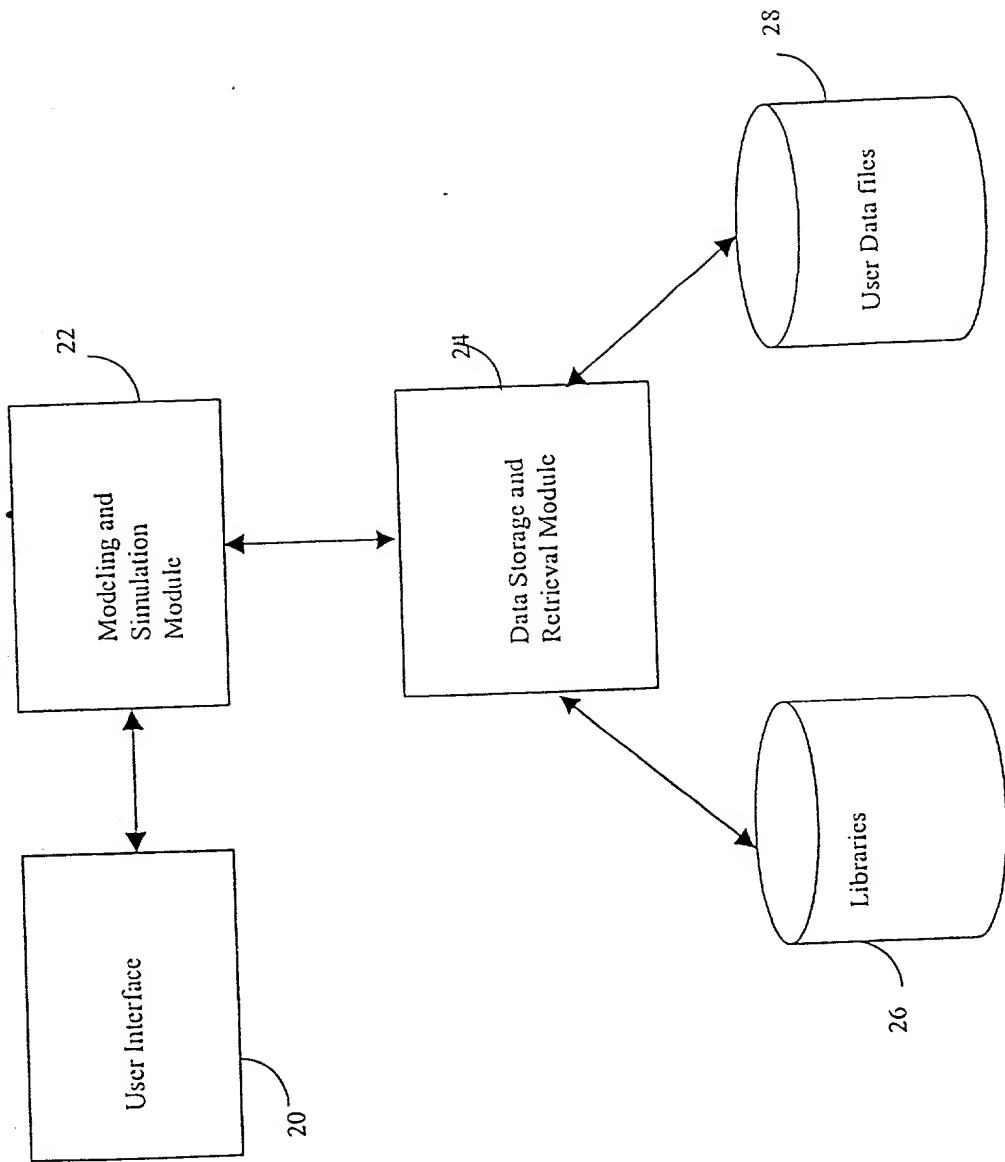


FIGURE 2

FIGURE 13, 54

Model Navigator

New | Model Library | User Models | Multiphysics | Preferences

Dimension
☒ 1-D ☒ 2-D

Independent variables:

AC Power Electromagnetics
 Conductive Media DC
 Diffusion
 Electrostatics
 Magnetostatics
Heat Transfer
 Incompressible Navier-Stokes
 Structural Mech., Plane Stre:
 Structural Mech., Plane Stra
 PDE, coefficient form
 PDE, general form

Conductive Media DC
Heat Transfer

Application mode name:

Dependent variables:

Solver type:

Solution form:

Application mode name:

Dependent variables:

Sub mode:

OK Cancel

31a 31b

FIGURE 2/4

PDE Specification/ht

Equation: $\rho \cdot C \cdot T' \cdot \nabla \cdot (k \nabla T) = Q + h \cdot (T_{\text{ext}} \cdot T) + C_{\text{trans}} \cdot (T_{\text{ambtrans}} \cdot T^4)$, T = temperature

Subdomain selection

1

Name: 1

☒ Active in this subdomain

PDE coefficients ☒ Unlock

Coefficient	Value	Description
ρ	8930	Density
C	340	Heat capacity
k	384	Coeff. of heat conduction
Q	$1./((10*(1+\alpha*(T-T0)))^4)$	Heat source
h_{trans}	0	Convect. heat transf. coeff.
T_{ext}	0	External temperature
C_{trans}	0	User-defined constant
T_{ambtrans}	0	Ambient temperature

☒ On top

OK Cancel Apply

60

62

62a

66

64

64a

FIGURE 3.5

70

Equation: $T = T_0$

Boundary selection

1
2
3
4
5
6
7

Name: 1

☒ Enable borders

Boundary coefficients ☒ Unlock

Quantity	Value	Description
<input type="radio"/> q	0	Heat flux
<input type="radio"/> h	0	Heat transfer coefficient
<input type="radio"/> T _{inf}	0	External temperature
<input type="radio"/> C	0	Problem-dependent constant
<input type="radio"/> T _{amb}	0	Ambient temperature
<input type="radio"/> $n \cdot (k \cdot \text{grad} T) = 0$		Insulation/symmetry
<input checked="" type="radio"/> T	300	Temperature
<input type="radio"/> T=0		Zero temperature

☒ On top OK Cancel Apply

72

74a

74

74b

FIGURE 4/6

80

Boundary Conditions/Coefficient View

Equation: $n \cdot (c \nabla u + \alpha u \gamma) + q \cdot u = g \cdot h \cdot \lambda \cdot h \cdot u = \dots$

82a, 82b, 82c, 82d, 84a, 84b, 84c, 84d

q | g | h | λ | α | c

Boundary selection

1
2
3
4

Name:

q coefficient

u	v	T	
1	0	0	ps
0	1	0	ps
0	0	0	ht

94

On top

OK

Cancel

Apply

92a, 92b, 92c

88

94

92a

92b

92c

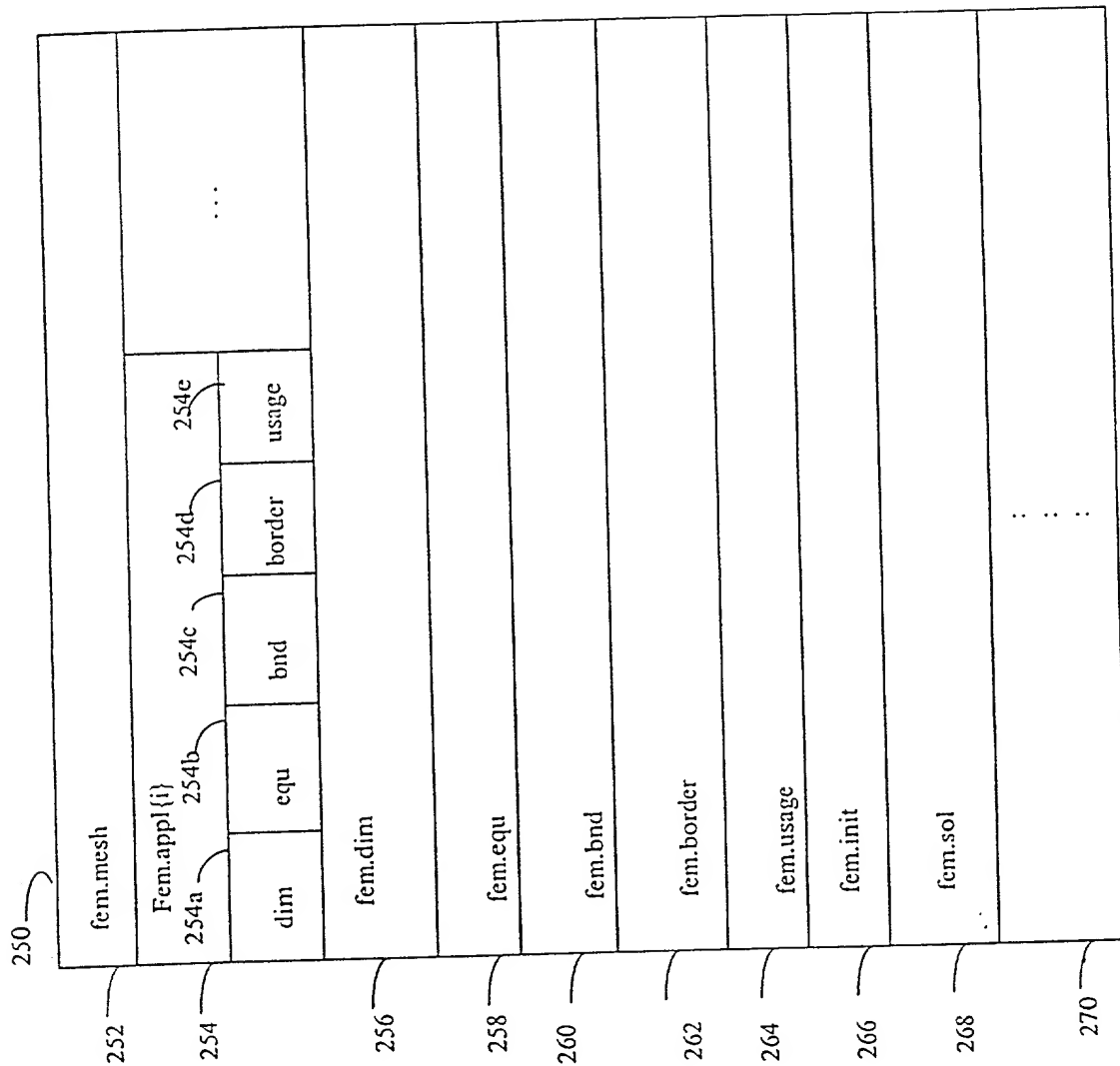


FIGURE 6A

FIGURE 5/7

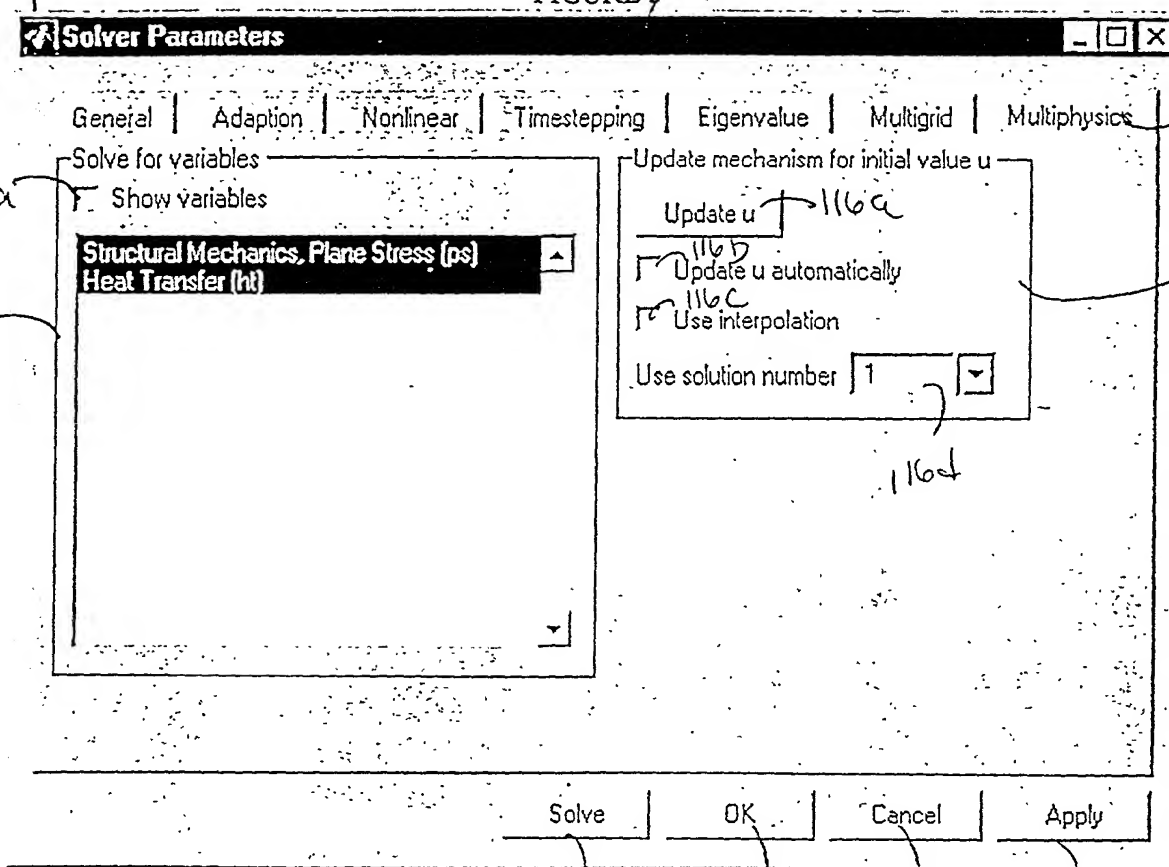


FIGURE 8

$$\left. \begin{aligned}
 & d_{a\ l k} \frac{\partial u_k}{\partial t} - \frac{\partial}{\partial x_j} \left(c_{l k j i} \frac{\partial u_k}{\partial x_i} + \alpha_{l k j} u_k - \gamma_{l j} \right) + \beta_{l k i} \frac{\partial u_k}{\partial x_i} + a_{l k} u_k = f_l \\
 & n_j \left(c_{l k j i} \frac{\partial u_k}{\partial x_i} + \alpha_{l k j} u_k - \gamma_{l j} \right) + q_{l k} u_k = g_l - h_{m l} \lambda_m \\
 & h_{m l} u_l = r_m
 \end{aligned} \right\} \begin{aligned}
 & \Omega \quad 142 \\
 & \partial \Omega \quad 146a \\
 & \partial \Omega \quad 146b
 \end{aligned} \quad 146$$

FIGURE 9

$$\left. \begin{aligned}
 & d_{a\ l k} \frac{\partial u_k}{\partial t} + \frac{\partial \Gamma_{l j}}{\partial x_j} = F_l \\
 & -n_j \Gamma_{l j} = G_l + \frac{\partial R_m}{\partial u_l} \lambda_m \\
 & 0 = R_m
 \end{aligned} \right\} \begin{aligned}
 & \Omega \quad 152 \\
 & \partial \Omega \quad 154a \\
 & \partial \Omega \quad 154b
 \end{aligned} \quad 154$$

FIGURE 10

$$\begin{array}{l}
 \gamma_{ij} = \Gamma_{ij} \\
 c_{ikjl} = -\frac{\partial \Gamma_{ij}}{\partial \left(\frac{\partial u_k}{\partial x_l} \right)} \\
 \beta_{lki} = -\frac{\partial F_l}{\partial \left(\frac{\partial u_k}{\partial x_l} \right)} \\
 g_l = G_l \\
 q_{lk} = -\frac{\partial G_l}{\partial u_k}
 \end{array}
 \quad
 \begin{array}{l}
 f_l = F_l \\
 a_{lkj} = -\frac{\partial \Gamma_{ij}}{\partial u_k} \\
 a_{lk} = -\frac{\partial F_l}{\partial u_k} \\
 r_l = R_l \\
 h_{lk} = -\frac{\partial R_l}{\partial u_k}
 \end{array}$$

FIGURE 11

$$\left. \begin{aligned}
 \Gamma_{lj} &= -c_{lkji} \frac{\partial u_k}{\partial x_i} - \alpha_{lkj} u_k + \gamma_{lj} \\
 F_l &= f_l - \beta_{lki} \frac{\partial u_k}{\partial x_i} - a_{lk} u_k \\
 G_l &= g_l - q_{lk} u_k \\
 R_m &= r_m - h_{ml} u_l
 \end{aligned} \right\}$$

FIG 12

$$\left. \begin{aligned}
 & \int_{\Omega} \left(\left(c_{lkji} \frac{\partial u_k}{\partial x_i} + \alpha_{lkj} u_k \right) \frac{\partial v}{\partial x_j} + \left(d_{al k} \frac{\partial u_k}{\partial t} + \beta_{lki} \frac{\partial u_k}{\partial x_i} + a_{lk} u_k \right) v \right) dx + \\
 & \int_{\partial\Omega} q_{lk} u_k v ds = \int_{\Omega} \left(\gamma_{lj} \frac{\partial v}{\partial x_j} + f_l v \right) dx + \int_{\partial\Omega} (g_l - h_{ml} \lambda_m) v ds \\
 & \int_{\partial\Omega} \mu h_{mk} u_k ds = \int_{\partial\Omega} \mu r_m ds
 \end{aligned} \right\}$$

FIG 13

$$302 \left\{ \begin{array}{l} \int_{\Omega} \left(\Gamma_{lj} \frac{\partial v}{\partial x_j} + F_l v - d_{alk} \frac{\partial u_k}{\partial t} v \right) dx + \int_{\partial\Omega} \left(G_l + \frac{\partial R^m}{\partial u_l} \lambda_m \right) v ds = 0 \\ \int_{\partial\Omega} R_m \mu ds = 0 \end{array} \right.$$

FIG 14

$$U_k(x) = \sum_{l=1}^{N_p} U_{l,k} \phi_l(x),$$

$$\Lambda_m(x) = \sum_{K=1}^{N_s} \sum_{L=1}^n \Lambda_{K,L,m} \psi_{K,L}(x)$$

FIG 15

$$\begin{aligned}
 & \int_{\tau} \left(c_{lkji} U_{I,k} \frac{\partial \phi_I}{\partial x_i} + \alpha_{lkj} U_{I,k} \phi_I \right) \frac{\partial \phi_J}{\partial x_j} dx + \\
 & \int_{\tau} \left(d_{alk} \frac{\partial U_{I,k}}{\partial t} \phi_I + \beta_{lki} U_{I,k} \frac{\partial \phi_I}{\partial x_i} + a_{lk} U_{I,k} \phi_I \right) \phi_J dx + \\
 & \int_{\partial \tau} q_{lk} U_{I,k} \phi_I \phi_J ds = \int_{\tau} \left(\gamma_{IJ} \frac{\partial \phi_J}{\partial x_j} + f_I \phi_J \right) dx + \\
 & \int_{\partial \tau} (g_I - h_{ml} \Lambda_{K,L,m} \Psi_{K,L}) \phi_J ds
 \end{aligned}$$

FIG 16

$$308 \int_{\hat{e}} h_{mk} U_{l,k} \phi_l \Psi_{K,L} ds = \int_{\partial \tau} r_m \Psi_{K,L} ds$$

FIG 17

$$3^2 \left\{ \int_{\tau} \left(\Gamma_{lj} \frac{\partial \phi_j}{\partial x_j} + F_l \phi_j - d_{alk} \frac{\partial u^k}{\partial t} \phi_j \right) dx + \int_{\partial \tau} \left(G_l + \frac{\partial R^m}{\partial u^l} \Lambda_{K,L,m} \Psi_{K,L} \right) \phi_j ds = 0 \right. \\ \left. \int_{\partial \tau} R_m \Psi_{K,L} ds = 0 \right.$$

FIG 18

$$\begin{aligned}
DA_{(J,l),(l,k)} &= \int_{\tau} d_{alk} \phi_I \phi_J dx \\
C_{(J,l),(l,k)} &= \int_{\tau} c_{lkji} \frac{\partial \phi_I}{\partial x_i} \frac{\partial \phi_J}{\partial x_j} dx \\
AL_{(J,l),(l,k)} &= \int_{\tau} a_{lkj} \phi_I \frac{\partial \phi_J}{\partial x_j} dx \\
BE_{(J,l),(l,k)} &= \int_{\tau} \beta_{lki} \frac{\partial \phi_I}{\partial x_i} \phi_J dx \\
A_{(J,l),(l,k)} &= \int_{\tau} a_{lk} \phi_I \phi_J dx \\
Q_{(J,l),(l,k)} &= \int_{\partial \tau} q_{lk} \phi_I \phi_J ds \\
GA_{(J,l)} &= \int_{\tau} \gamma_{lj} \frac{\partial \phi_J}{\partial x_j} dx \\
F_{(J,l)} &= \int_{\tau} f_l \phi_J dx \\
G_{(J,l)} &= \int_{\partial \tau} g_l \phi_J ds \\
H_{(K,L,m),(l,k)} &= \int_{\partial \tau} h_{mk} \phi_I \Psi_{K,L} ds \\
R_{(K,L,m)} &= \int_{\partial \tau} r_m \Psi_{K,L} ds
\end{aligned}$$

FIG 19

$$\left. \begin{array}{l} (c) \\ \end{array} \right\} \begin{array}{l} DA \frac{\partial U}{\partial t} + (C + AL + BE + A + Q)U + H^T \Lambda = GA + F + G \\ HU = R \end{array}$$

FIG 20

$$\left\{ \begin{array}{l} DA \frac{\partial U}{\partial t} + H^T \Lambda = GA + F + G \\ R = 0 \end{array} \right.$$

FIG 21

$$\begin{cases} J(U^{(k)}) \Delta U^{(k)} = -\rho(U^{(k)}) \\ U^{(k+1)} = U^{(k)} + \lambda_k \Delta U^{(k)} \end{cases}$$

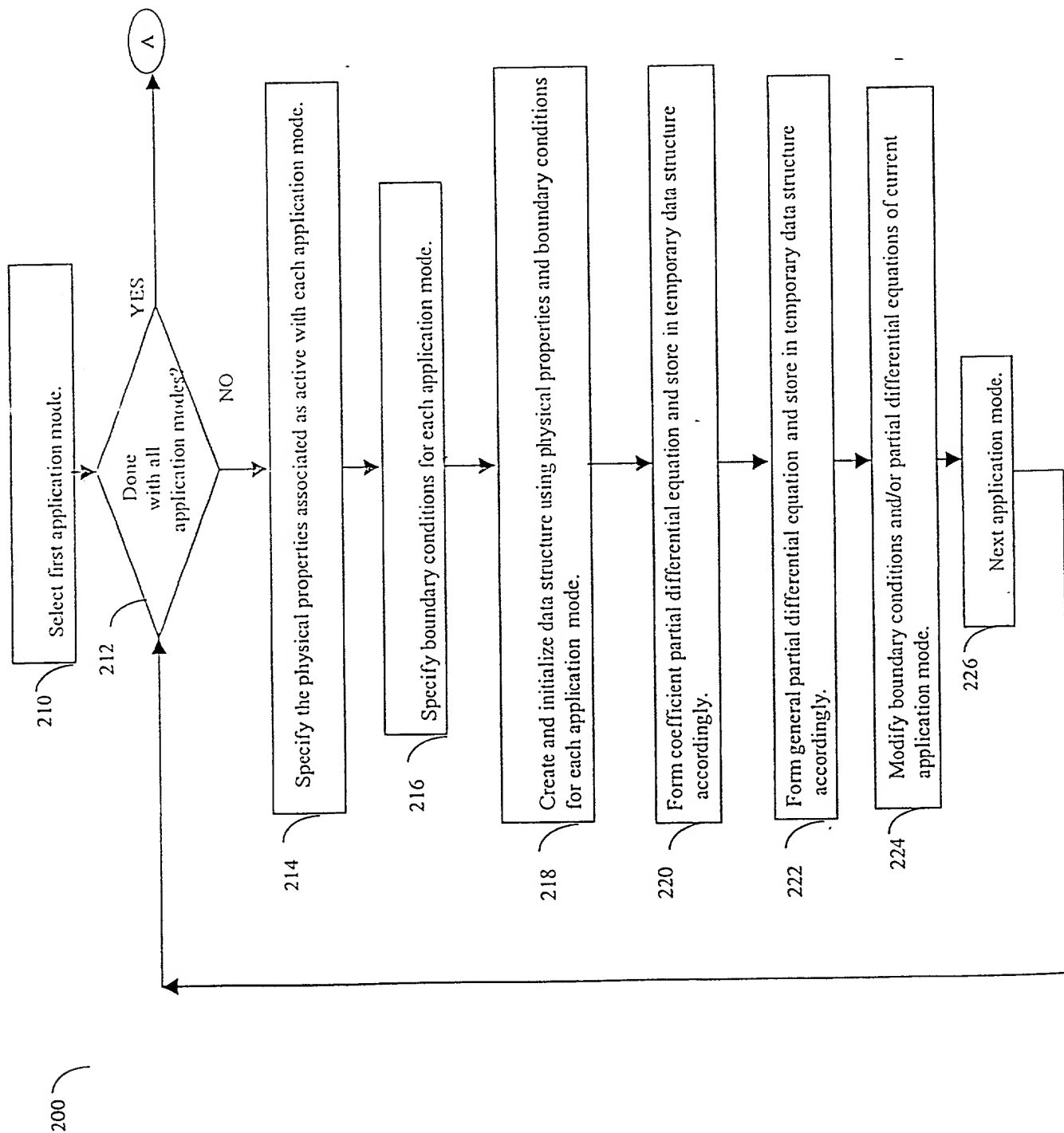


FIGURE 22

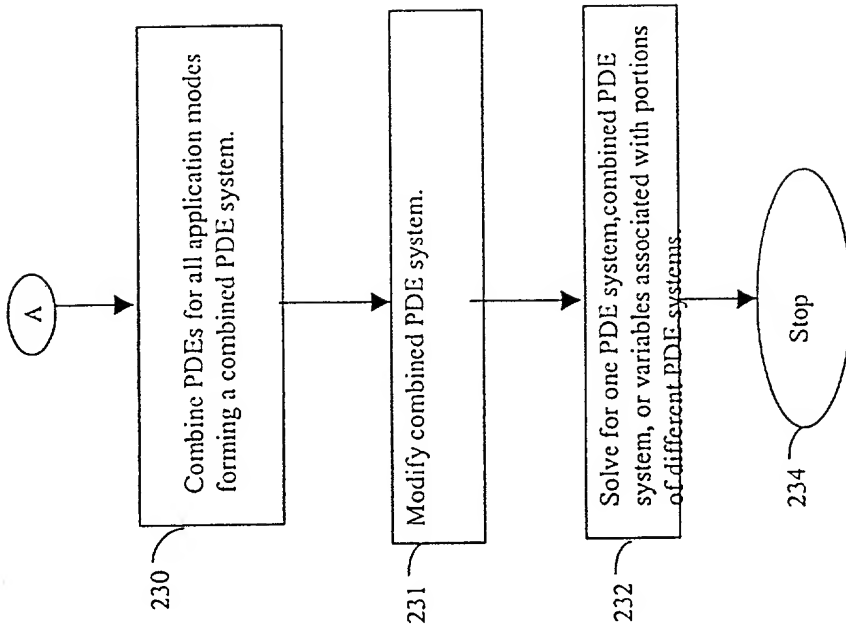
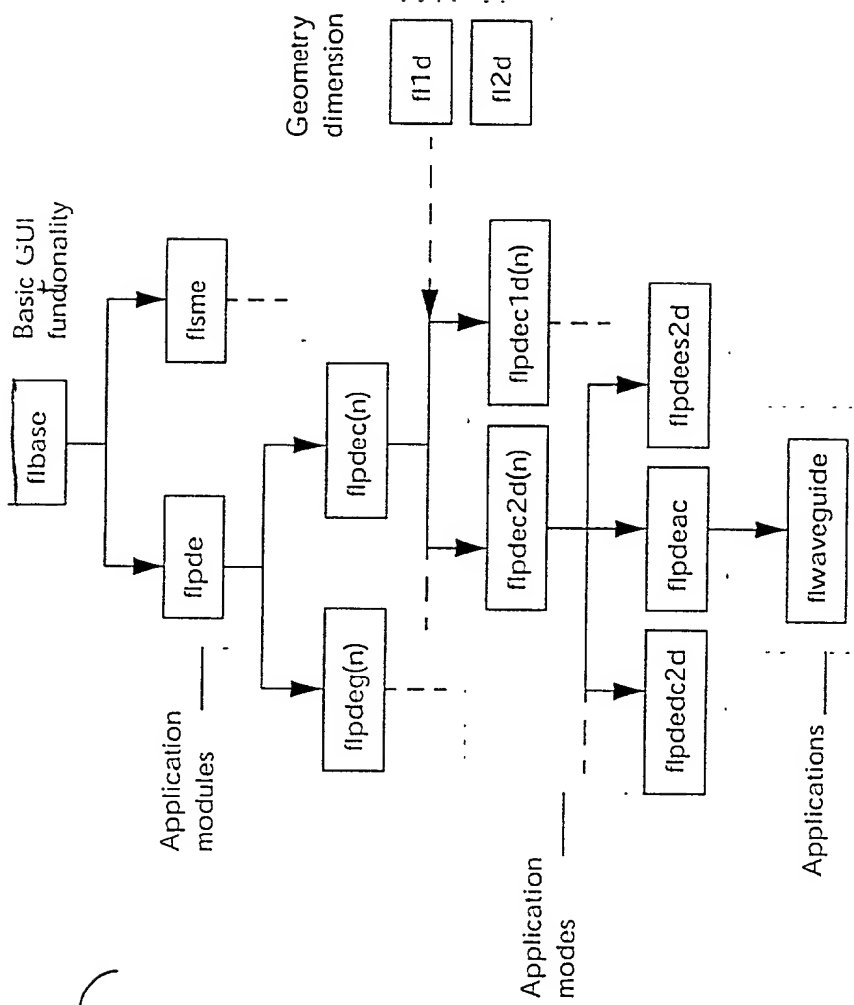


FIGURE 23



The class hierarchy of FEMLAB

Figure 24

S02

1-D Physics Application Modes		
Application mode	Class name	Parent class
Diffusion	flpdedf1d	flpdedf
Heat Transfer	flpdeht1d	flpdeht

S04

: 1-D PDE Application Modes		
Application mode	Class name	Parent class
Coefficient PDE model, n variables	flpdec1d(n)	flpdec(n)
General PDE model, n variables	flpdeg1d(n)	flpdeg(n)

FIGURE 25

2-D Physics Application Modes

Application mode	Class name	Parent class
AC Power Electromagnetics	flpdeac	flpdec2d
Conductive Media DC	flpdedc2d	flpdedc
Diffusion	flpdedf2d	flpdedf
Electrostatics	flpdees2d	flpdees
Magnetostatics	flpdems2d	flpdems
Heat Transfer	flpdeht2d	flpdeht
Incompressible Navier-Stokes	flpdens2d	flpdens
Structural Mechanics, Plane Stress	flpdeps	flpdec2d
Structural Mechanics, Plane Strain	flpdepn	flpdec2d

Sub

PDE Application Modes		
Application mode	Class name	Parent class
Coefficient PDE model, n variables	flpdec2d(n)	flpdec(n)
General PDE model, n variables	flpdeg2d(n)	flpdeg(n)

Sub

FIGURE 26

Figure 27

Application Object Properties		
Property name	Description	Data type
dim	Names of the dependent variables	Cell array of strings
form	PDE form	String (coefficient/general)
name	Application name	String
parent	Parent class names	String, cell array of strings, or the empty matrix
sdim	Names of the independent variables (space dimensions)	Cell array of strings
submode	Name of current submode	String (std/wave)
tdiff	Time differentiation flag	String (on/off)

51

```

function obj = myapp()
%MYAPP Constructor for a FEMLAB application object.
Siz obj.name = 'My first FEMLAB application';
    obj.parent = 'flpdeht2d';

% MYAPP is a subclass of FLPDEHT2D:
    p1 = flpdeht2d;
    obj = class(obj,'myapp',p1);
    set(obj,'dim',default_dim(obj));

```

FIGURE 28

Physics Modeling Methods

Function	Purpose
appspec	Return application specifications.
bnd_compute	Convert application-dependent boundary conditions to generic boundary coefficients.
default_bnd	Default boundary conditions.
default_dim	Default names of dependent variables.
default_equ	Default PDE coefficients/Material parameters.
default_init	Default initial conditions.
default_sdim	Default space dimension variables.
default_var	Default application scalar variables.
dim_compute	Return dependent variables for an application.
equ_compute	Convert application-dependent material parameters to generic PDE coefficients.
form_compute	Return PDE form.
init_compute	Convert application-dependent initial conditions to generic initial conditions.
posttable	Define assigned variable names and post-processing information.

514

FIGURE 29

Model Navigator

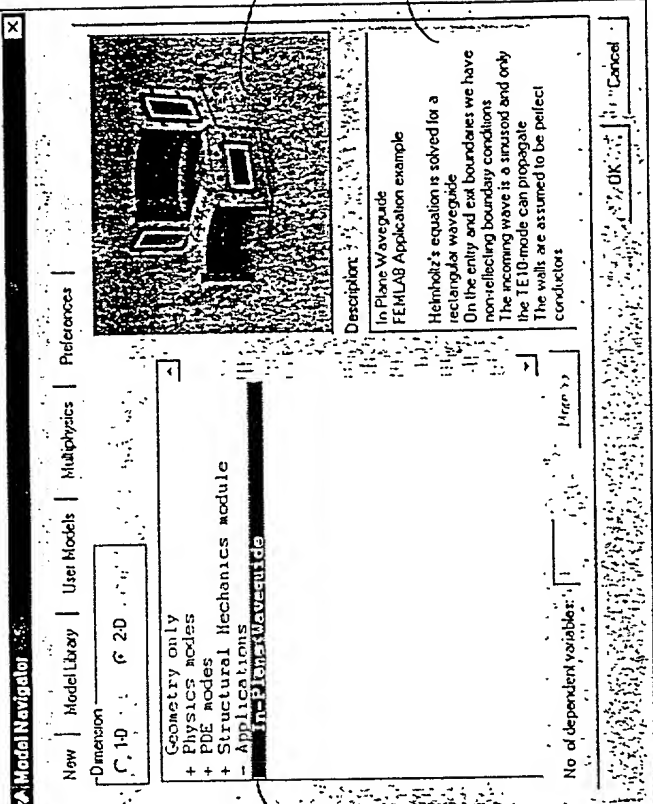


FIGURE 30

$$530 \quad \boxed{\Delta E_z + (2\pi i k)^2 E_z = 0}$$

$$532 \quad \boxed{k = \frac{1}{\lambda} = \frac{f}{c}}$$

$$534 \quad \boxed{\vec{n} \cdot (\nabla E_z) + 2\pi i k_x E_z = 4\pi i k_x \sin\left(\frac{\pi}{d}(y - y_0)\right)}$$

$$536 \quad \boxed{k^2 = k_x^2 + k_y^2}$$

$$538 \quad \boxed{k_x = \sqrt{\frac{1}{\lambda^2} - \frac{1}{(2d)^2}}$$

$$540 \quad \boxed{\vec{n} \cdot (\nabla E_z) + 2\pi i k_x E_z = 0}$$

$$542 \quad \boxed{E_z = 0}$$

$$544 \quad \boxed{f_c = \frac{c}{2d}}$$

FIGURE 31

550

```

function obj = flwaveguide(varargin)
%FLWAVEGUIDE Constructor for a Waveguide application object.

obj.name = 'In-Plane Waveguide';
obj.parent = 'flpdeac';

% FLWAVEGUIDE is a subclass of FLPDEAC:
p1 = flpdeac;
obj = class(obj,'flwaveguide',p1);
set(obj,'dim',default_dim(obj));

```

FIGURE 32

552

fem.user fields	
Field	Description
geomparam	1-by-2 structure of geometry parameters.
entrybnd	Index to the entry boundary.
exitbnd	Index to the exit boundary.
freqs	Frequency vector

FIGURE 33

554

fem.user fields	
Field	Description
startpt	Index of the lower left corner point of the waveguide.
type	Type of waveguide. ('straight' or 'elbow')

FIGURE 34

556

geomparam fields			
Field	Description	Defaults for elbow	Defaults for straight
entrylength	Length of the entrance part of the waveguide.	0.1	0.1
exitlength	Length of the exit part of the waveguide.	0.1	Not used
radius	Outer radius of the waveguide bend.	0.05	Not used
width	Width of the waveguide.	0.025	0.025
cavityflag	Turn resonance cavity on or off.	0	0
cavitywidth	Width of the resonance cavity.	0.025	0.025
postwidth	Width of the protruding posts.	0.005	0.005
postdepth	Depth of the protruding posts.	0.005	0.005

FIGURE 35

Model Navigator

New | Model Library | User Models | Multiphysics | Preferences

Geometry name: **Geom1** Add **612/612A** **620**

Dimension: **2D** **2D** **3D** **602**

Independent variables: **xyz**

Solver type: **Time dependent** **622**

Solution form: **General**

Geom1: Conductive media DC
Geom1: Heat transfer

Application mode name: **ht**
Dependent variables: **T** **624**
Submode: **Standard**

Application mode name: **ht2**
Dependent variables: **T2** **616**
Element: **Lagrange - Quadratic** **618**

OK Cancel

614

606

608

610

600

Figure 36

626

Subdomain Settings/es

Equation: $\nabla \cdot (\epsilon \nabla V) = \rho$, $\epsilon = \epsilon(V)$, $V = \text{electric potential}$

Coefficients | Init | Element | **802**

Domain selection: **2**

Name: **1**

☐ Select by group
☒ Active in this domain

Element settings ☒ Use default element: **Lagrange - Quadratic**

Coefficient	Value	Description
shape	shlag(2,V)	Shape function
qporder	4	Integration order
cporder	2	Constraints order

☒ On top **OK** **Cancel** **Apply**

802

Figure 2

Subdomain Settings/c1

Equation: $\nabla \cdot (c \nabla (u - x u)) + a u + \beta \nabla u = f$

Coefficients: ☐ Init ☐ Element ☐ Weak ☐ Weak complement ☒ Unlink

Domain selection: ☐ 1 ☒ 2

Name:

☐ Select by group

☒ Active in this domain

Term	Value	Description
weak	0	Weak term
dweak	0	Time-dep. weak term
constr	0	Constraint

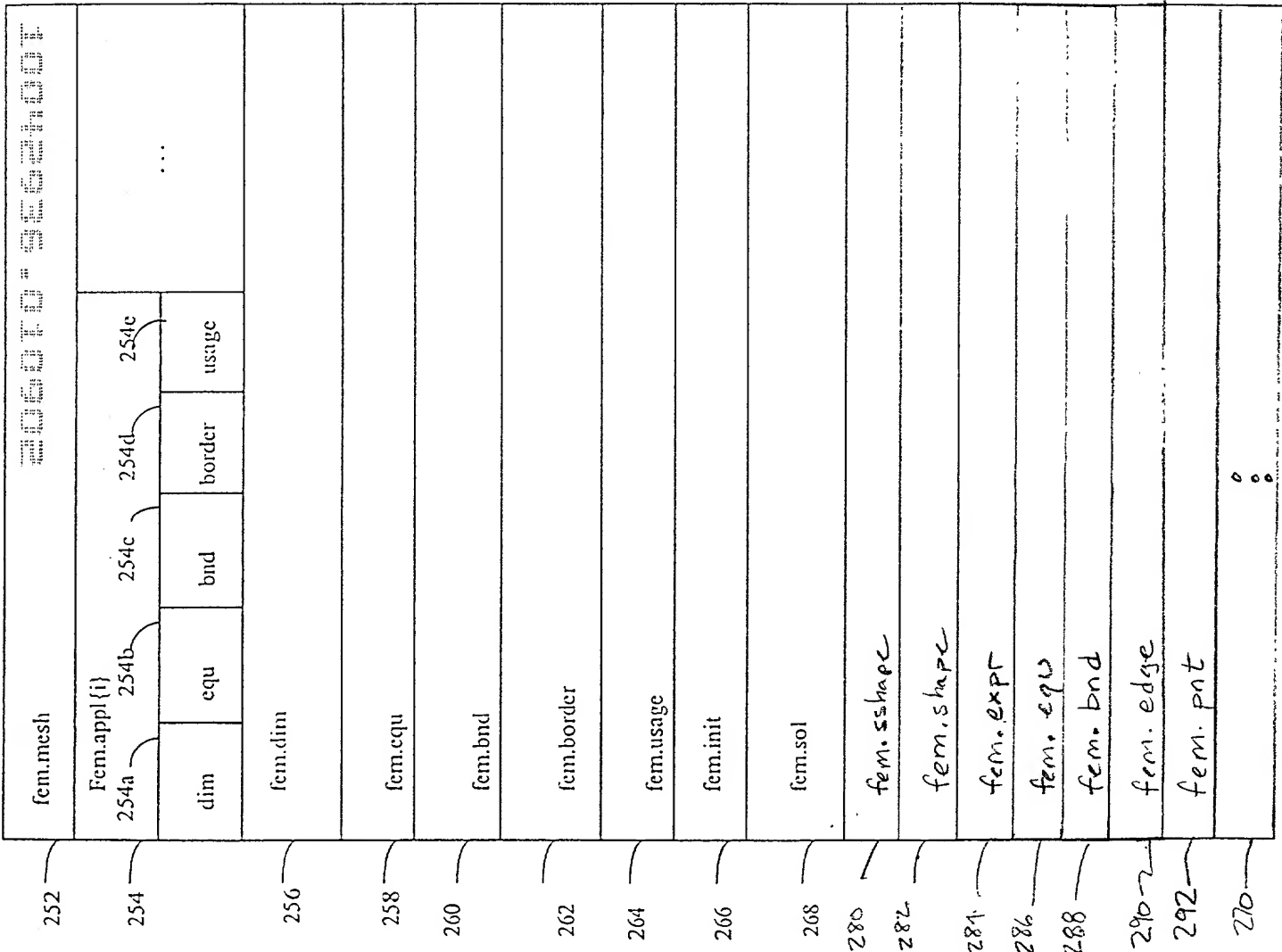
900 906 907

On top ☒ OK Cancel Apply

Figure 39

900

250



1000

Figure 40

$$\left\{ \begin{aligned} & 0 = \int_{\Omega} W^{(2)} dA + \int_B W^{(1)} ds + \sum_P W^{(0)} + \\ & + \int_{\Omega} v_l \frac{\partial R_m^{(2)}}{\partial u_l} \mu_m^{(2)} dA + \int_B v_l \frac{\partial R_m^{(1)}}{\partial u_l} \mu_m^{(1)} ds + \sum_P v_l \frac{\partial R_m^{(0)}}{\partial u_l} \mu_m^{(0)} \end{aligned} \right.$$

$$\left\{ \begin{aligned} 0 &= R^{(2)} && \text{on } \Omega \\ 0 &= R^{(1)} && \text{on } B \\ 0 &= R^{(0)} && \text{on } P \end{aligned} \right.$$

1100 Figure 41

$$W_l^{(n)} = W_l^{(n)} + \Gamma_{ij} \frac{\partial v_l}{\partial x_j} + F_l v_l$$

$$W_l^{(n)} = W_l^{(n)} + d_{alk} \frac{\partial u_k}{\partial t} v_l$$

$$W_l^{(n-1)} = W_l^{(n-1)} + G_l v_l$$

$$R_m^{(n)} = R_m$$

1200

Figure 42

Point Settings/c1

Domain selection

1

2

3

4

5

6

7

8

Name: 1

Select by group

Weak complement ☒ Unlabeled

Term	Value	Description
weak	0	Weak term
dweak	0	Time-dep. weak term
constr	0	Constraint

☒ On top

OK

Cancel

Apply




 Figure 9

Edge settings/ct

Domain selection: 1 2 3 4 5 6 7 8

Name: 1 ☐ Select by group

☒ Weak complement ☒ Unchecked

Term	Value	Description
weak	0	Weak term
dweak	0	Time-dep, weak term
constr	0	Constraint

1408

☒ On top ☐ OK

↑
1400
Figure 44-

Coupling Variable Settings

Variables | Source | Destination |

Name: Type: Defined from -> Available in:

Name	Type	Defined from	Available in
c1	scalar	Geom1:sub	-> Geom2:bn
c2	extr	Geom1:bn	-> Geom1:pnt

Variable name: c2

Variable type: extrusion

Add

Delete

☒ On top

OK

Cancel

Apply

1500A

1502

1504

1506

1508

Figure 45A

1500

1500

Coupling Variable Settings

Variables | Source | Destination

Variable: c2

Domain selection: **Geom1** | **boundary**

Level: 1 2 3 4 5 6 7 0

Select by group

Definition ☒ Copy from 3

Expression:

Integration type:

Local mesh transformation:

x y z

1502 1504 1506 1508 150a 150b 150c

☒ On top OK Cancel Apply

Figure 45B

206010 1500C

4 Coupling Variable Settings

Variables | Source | Destination

Variable: c2

Domain selection

Geometry:

Level:

☐ Select by group

Definition ☒ Copy from 1

☐ Active in this domain

Evaluation point transformation:

	x	y	z
1			
2			
3			
4			
5			
6			
7			
8			

☐ On top

1572a
1572b
1572c

1500

Figure 45c

Expression Variable Settings

Variables | Definition

Variable: em_s

Domain selection: ☐ Copy from:

Geometry: Geom1

Level: subdomain

☐ Select by group

Expression: u*sin(u)

☒ On top

OK Cancel Apply

1600

Figure 47

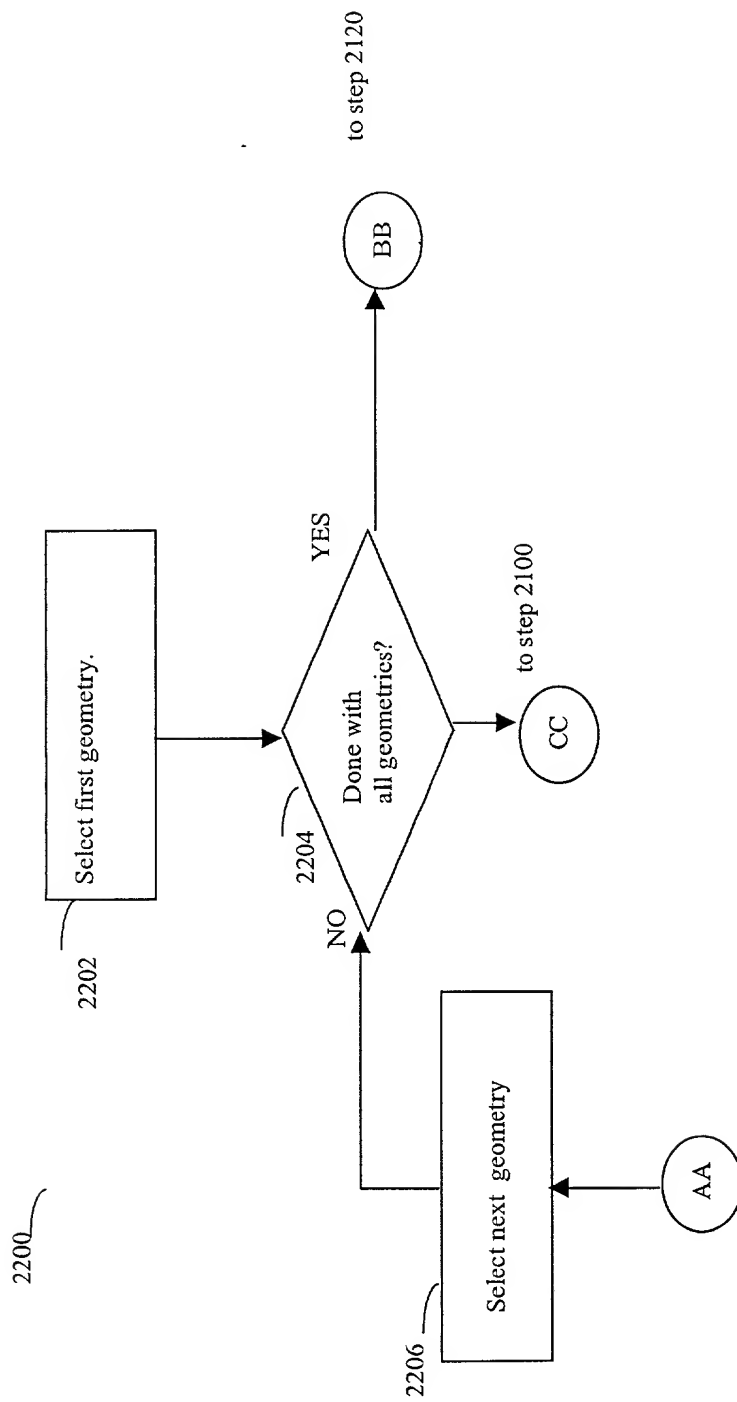


FIGURE 48

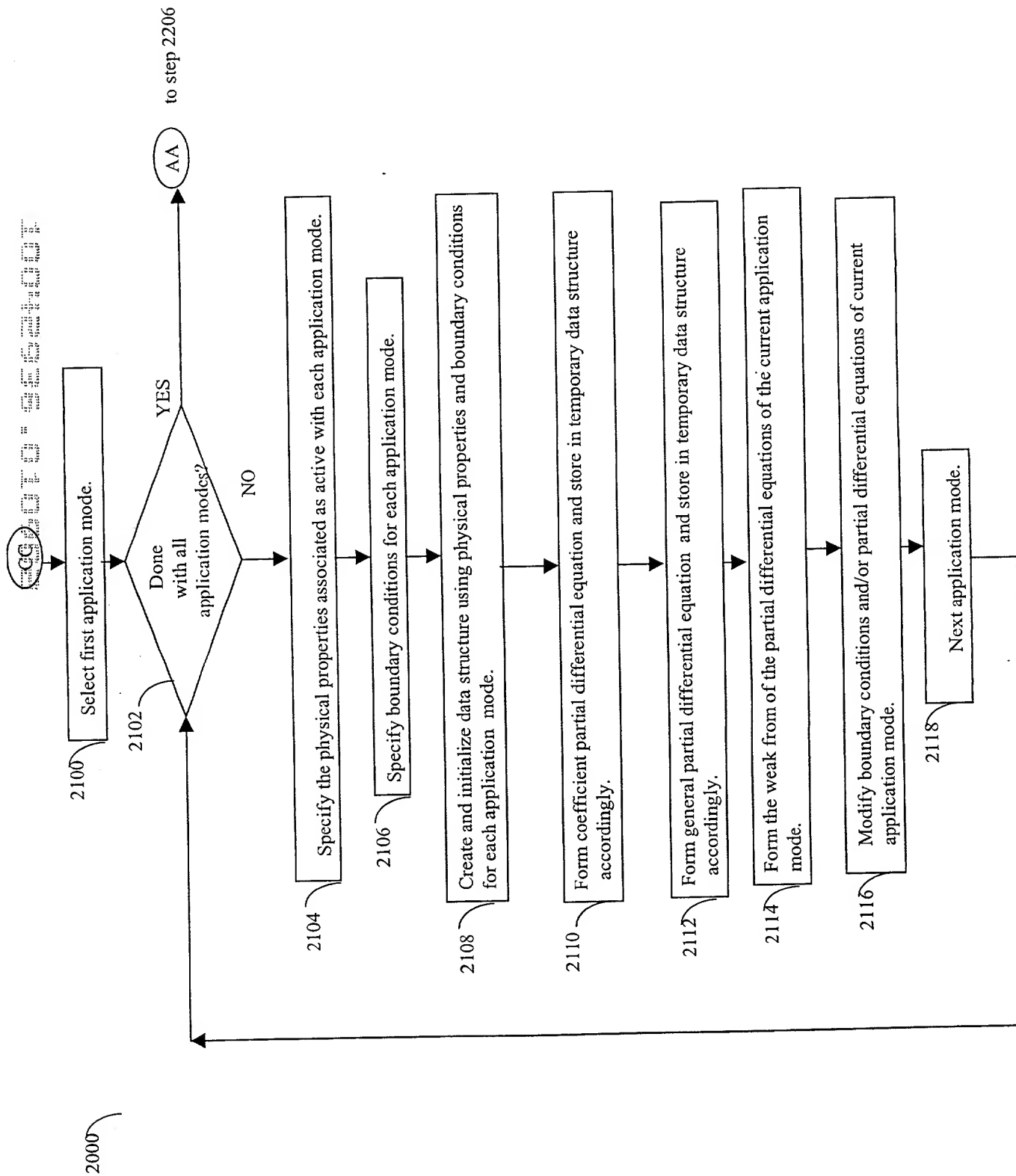


FIGURE 49

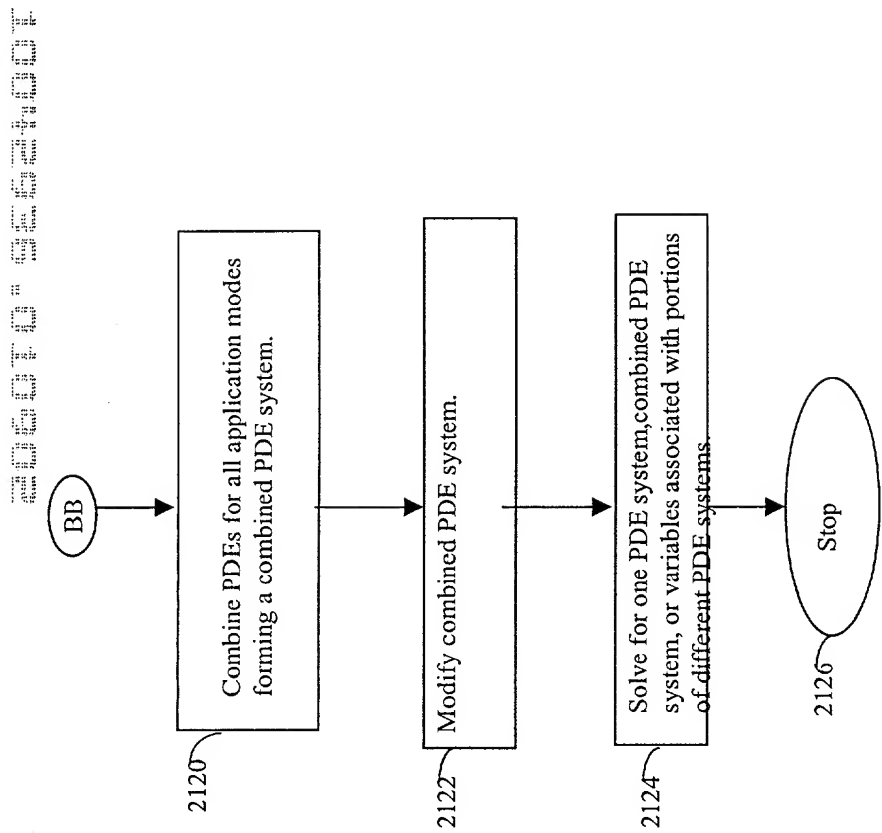


FIGURE 50

2124

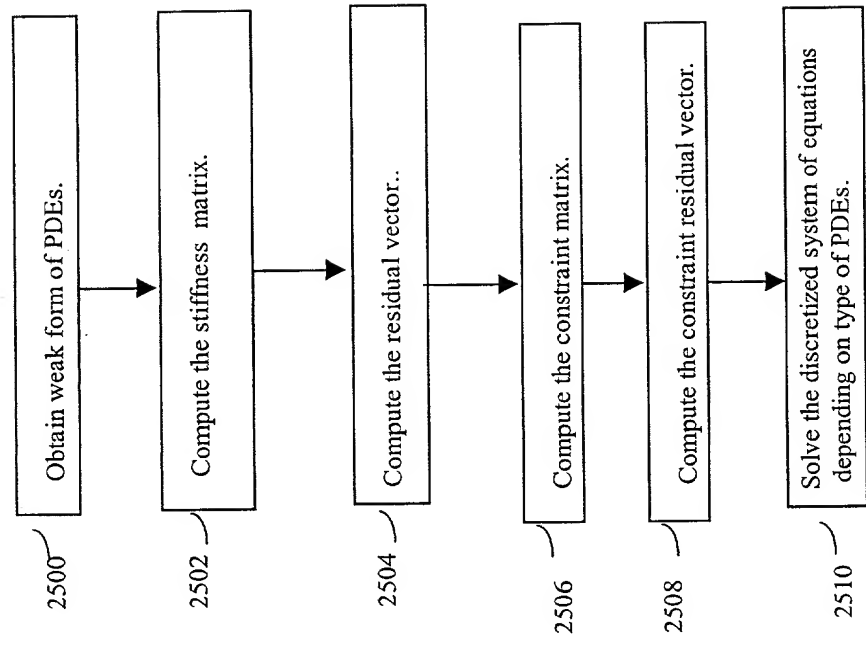


FIGURE 51

COMPUTE STIFFNESS MATRIX

2502

2550 2552 2554 2556 2558 2560 2562 2564 2566 2568

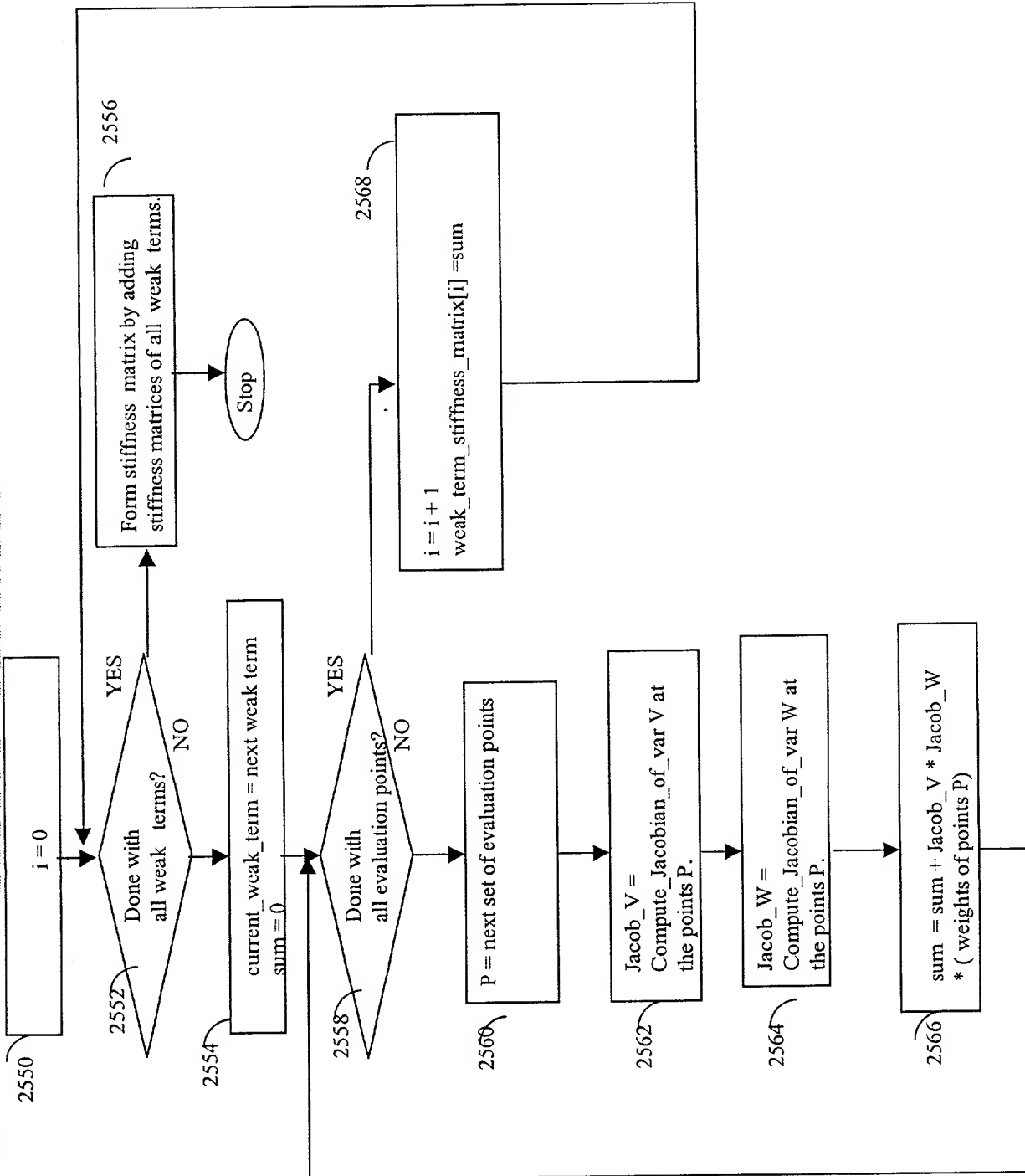


FIGURE 52

COMPUTE RESIDUAL VECTOR

2504

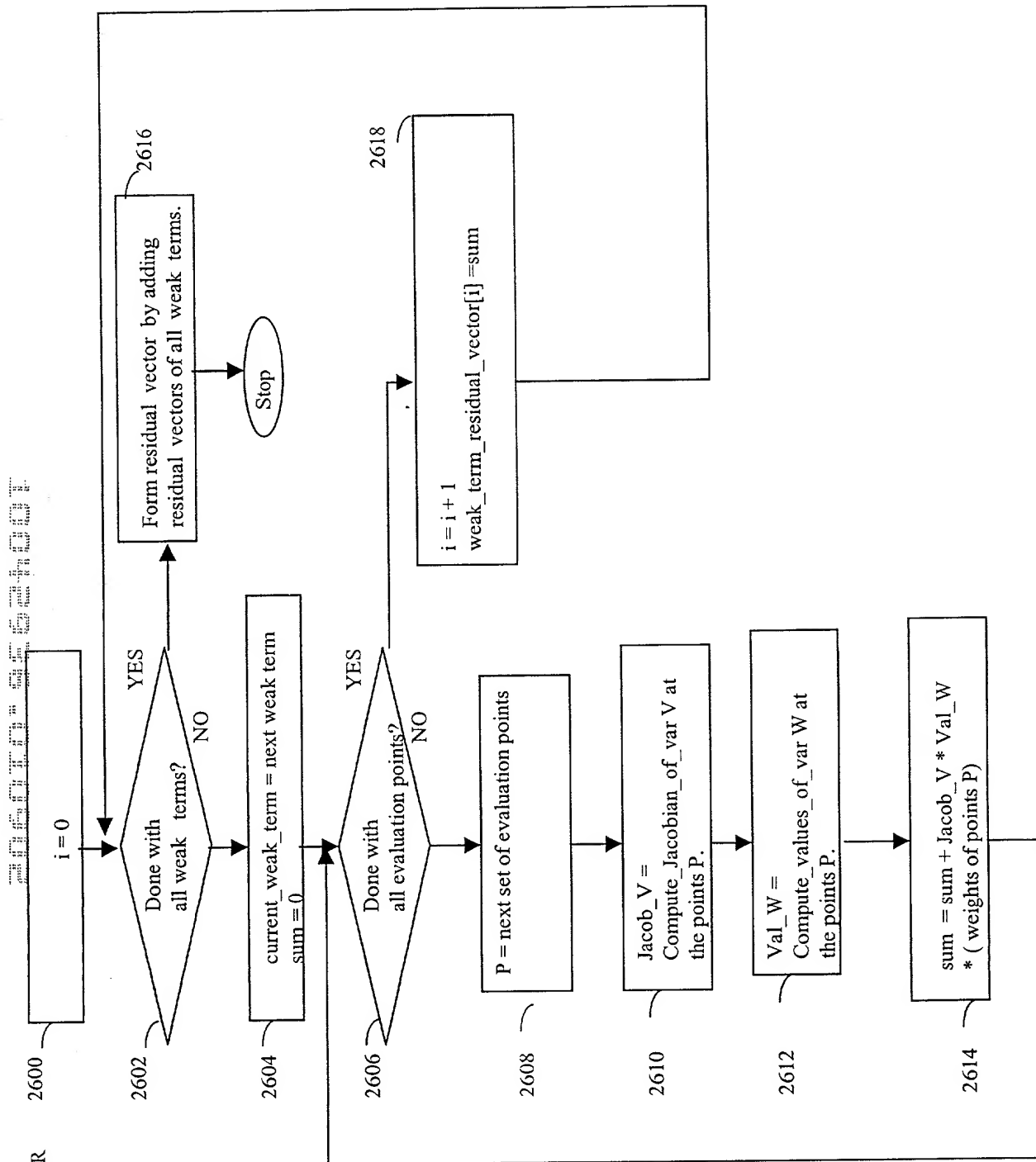


FIGURE 53

COMPUTE CONSTRAINT MATRIX

2506

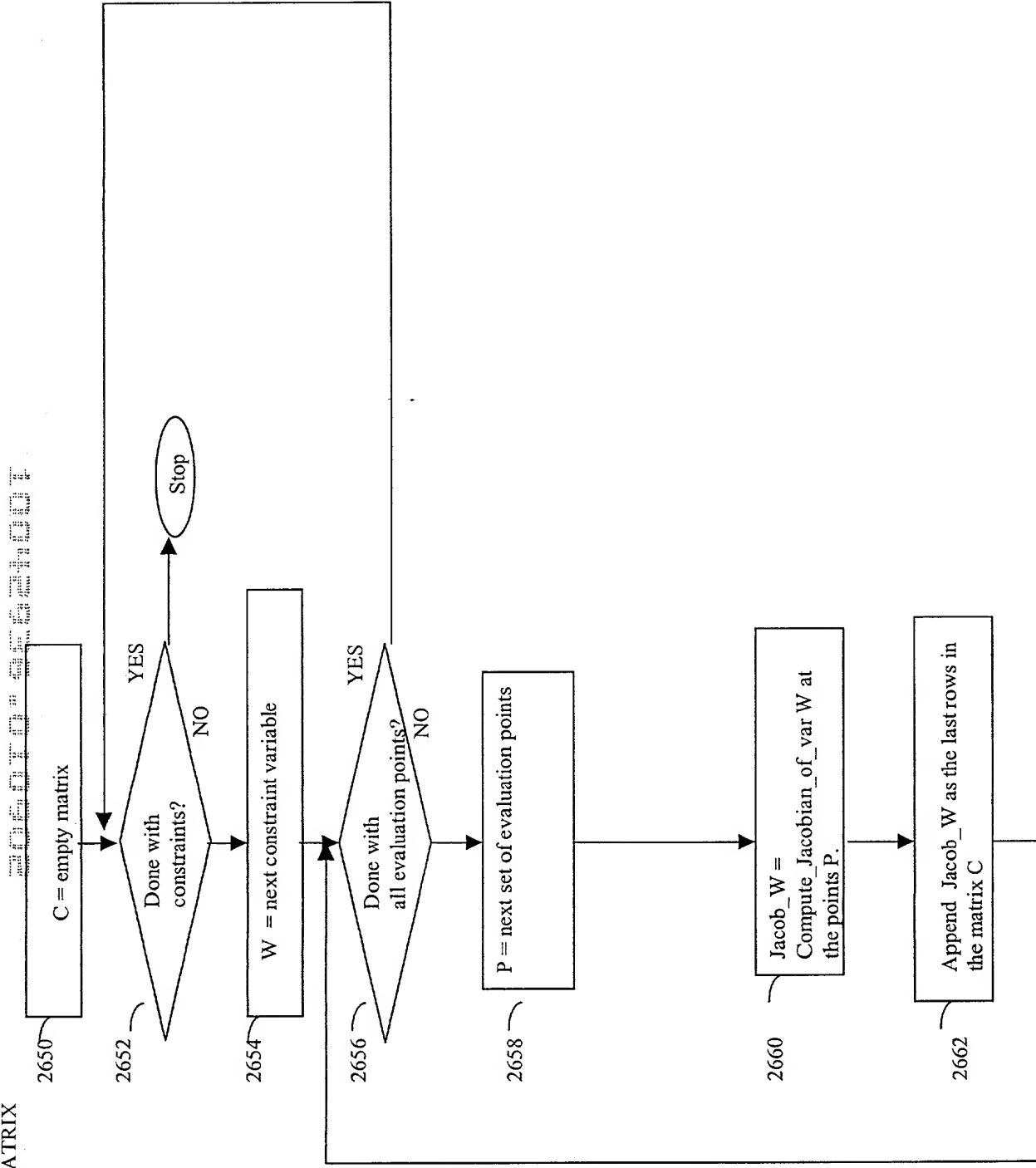


FIGURE 54

COMPUTE CONSTRAINT RESIDUAL VECTOR

2508

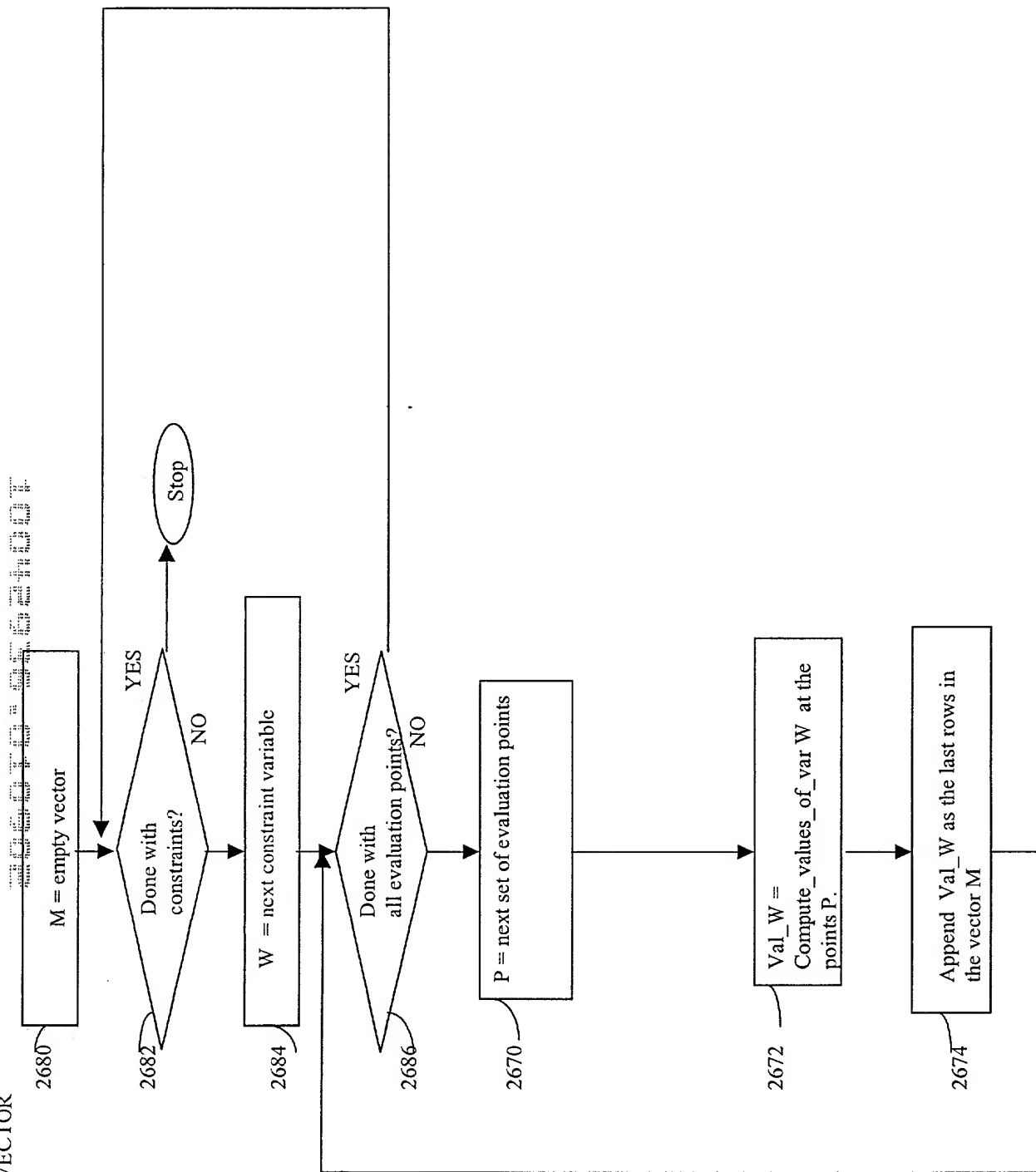


FIGURE 55A

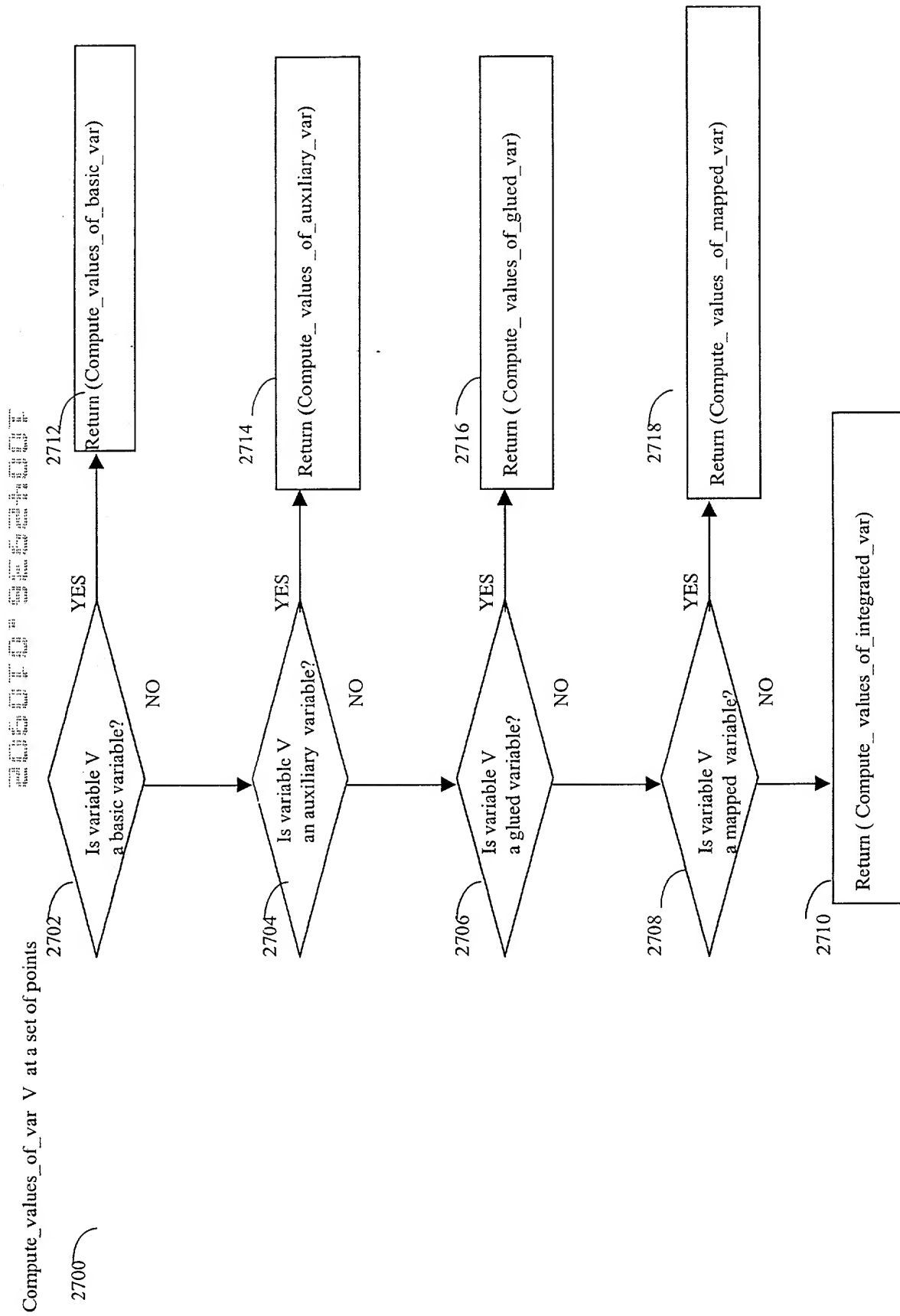


FIGURE 55B

Compute_values_of_basic_var at a set of points P

Return the sum of the values of the basic variables at the points P.

2720

Return the sum $\sum U_i * F_i(p_j)$, where the sum is taken over all indices i of the degrees of freedom, for p_j in the set P .

FIGURE 55C

Compute_values_of_auxiliary_var at a set of points P

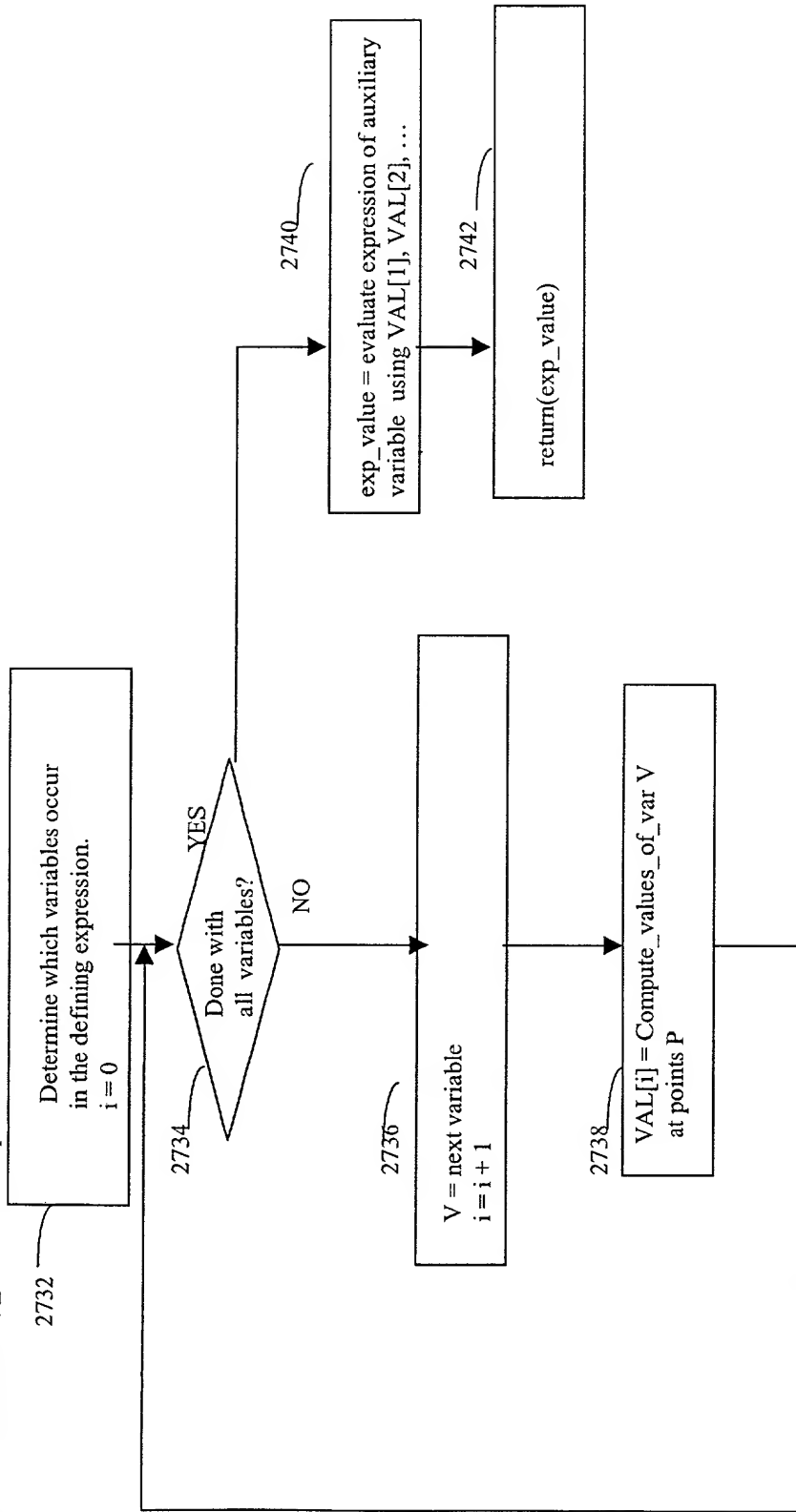


FIGURE 55D

Compute_values_of_glued_var at a set of points P

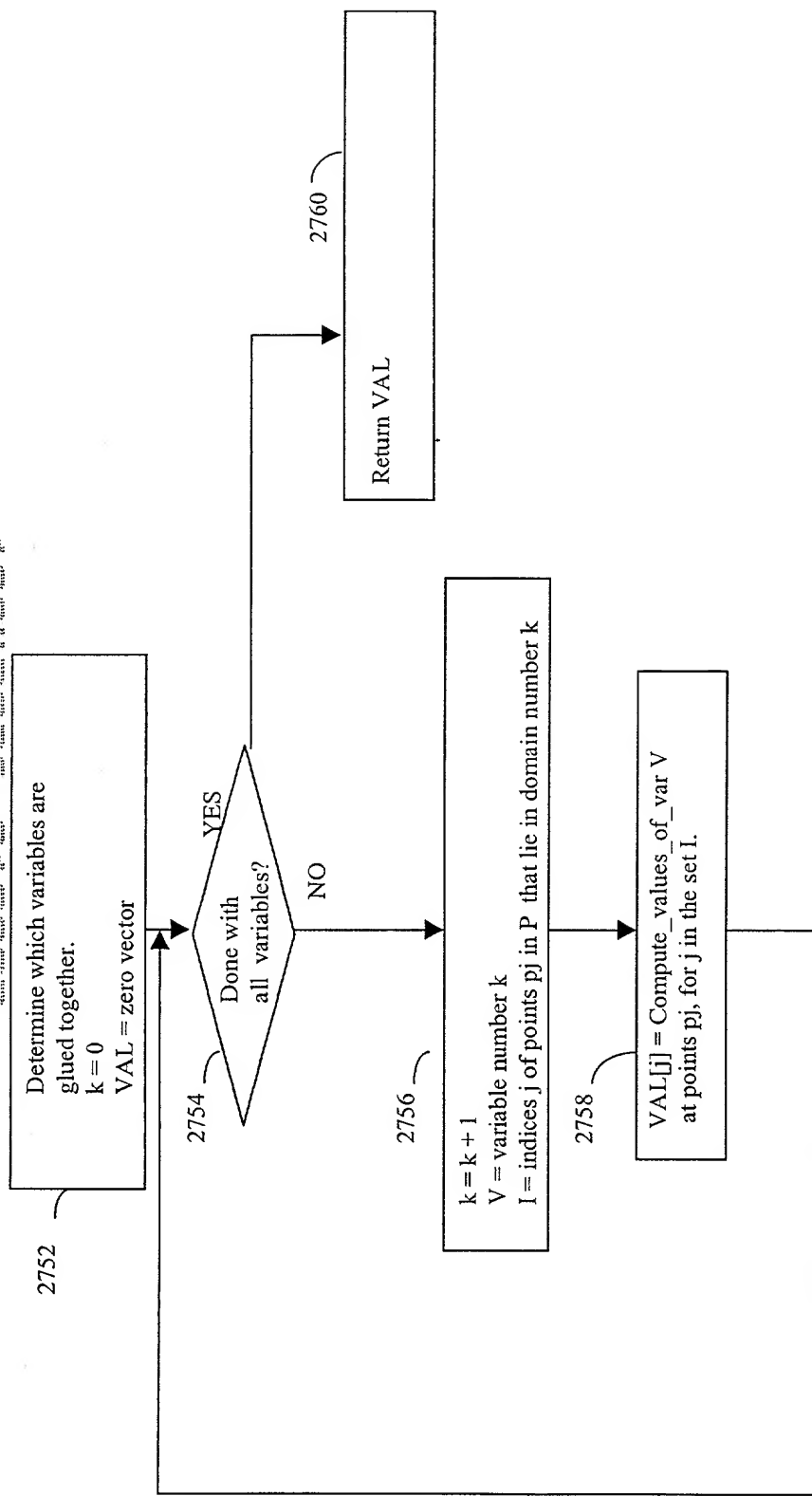


FIGURE 55E

Compute_values_of_mapped_var at a set of points P

2780

2782 2784 2786 2788

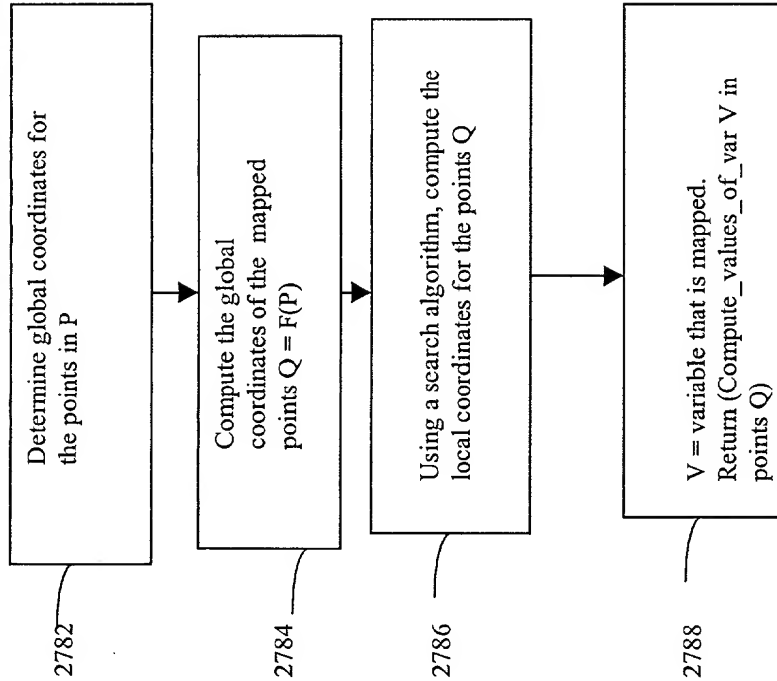


FIGURE 55F

Compute_values_of_integrated_var at a set of points P

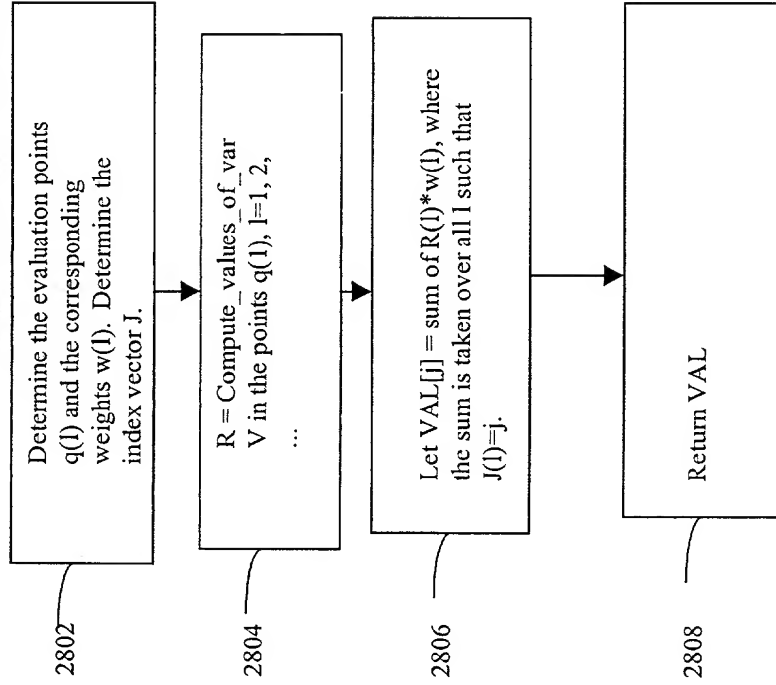


FIGURE 55G

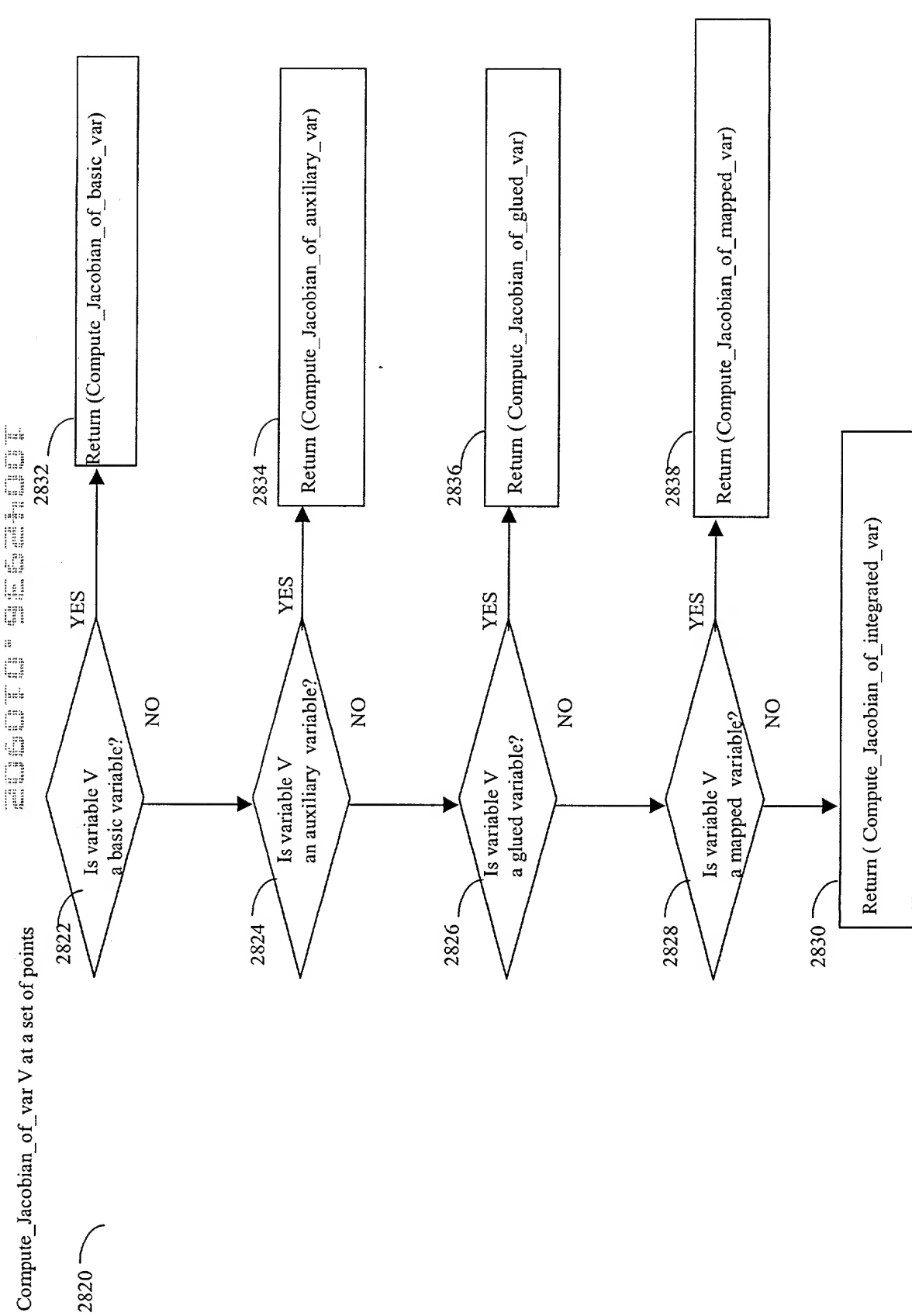


FIGURE 55H

2850

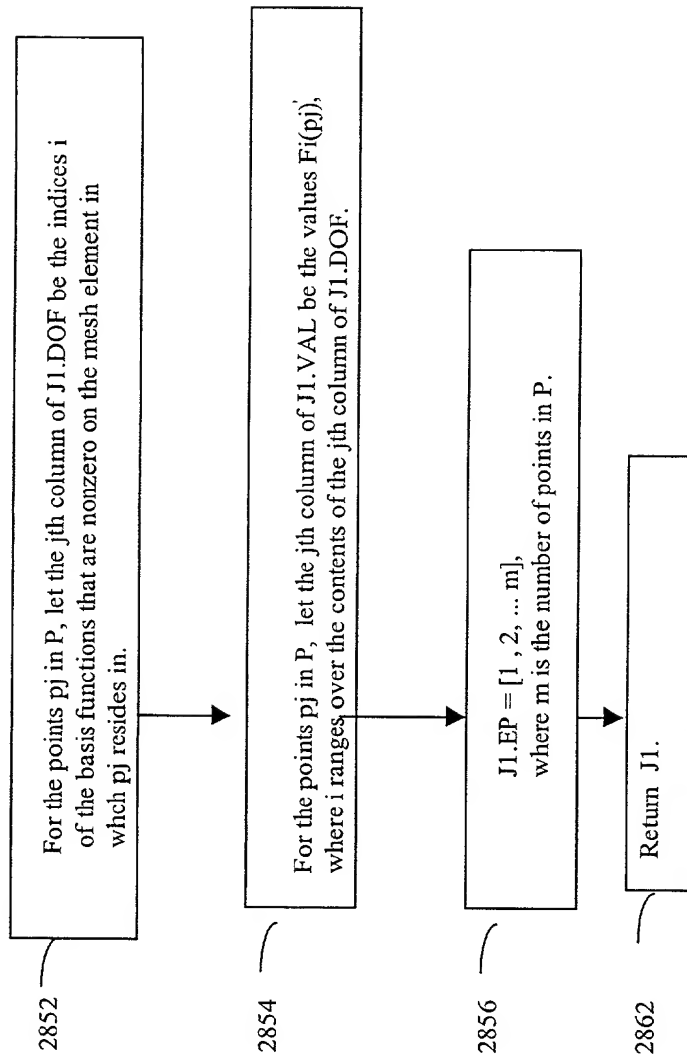


FIGURE 551

Compute_Jacobian_auxiliary_var at a set of points P

2880

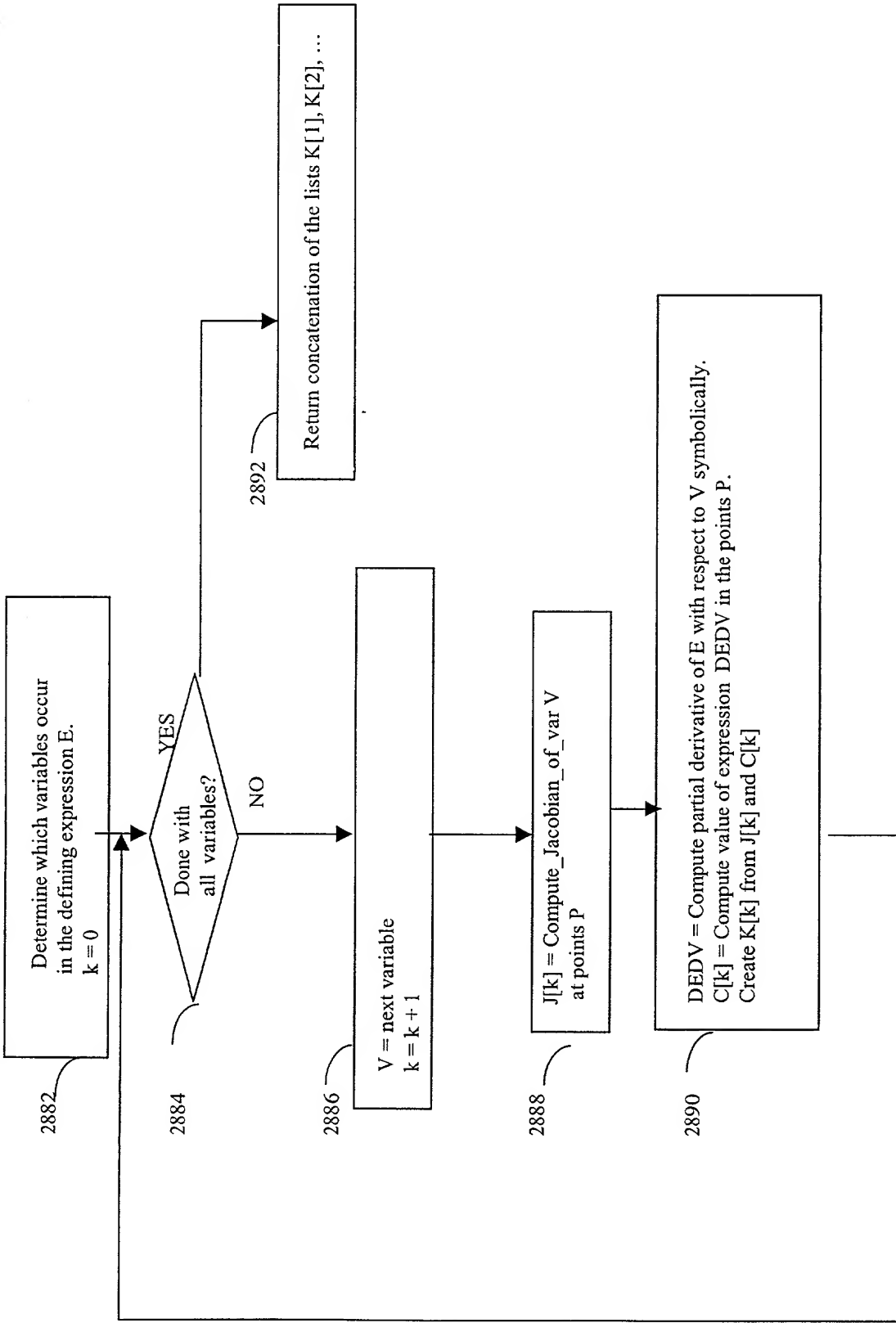


FIGURE 55J

Compute_Jacobian_of_glued_var at a set of points P

2900

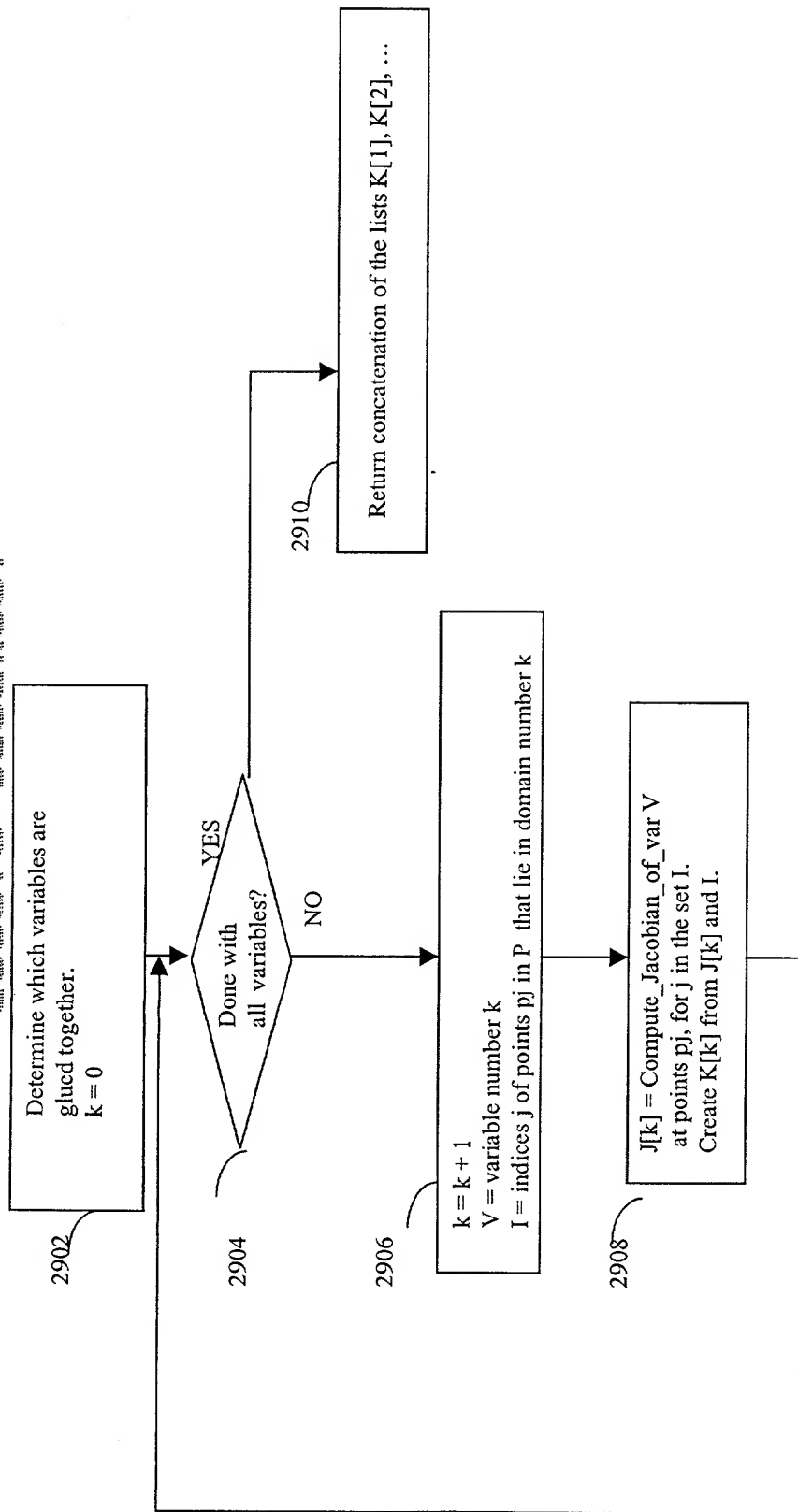


FIGURE 55K

Compute_Jacobian_of_mapped_var at a set of points P

2920

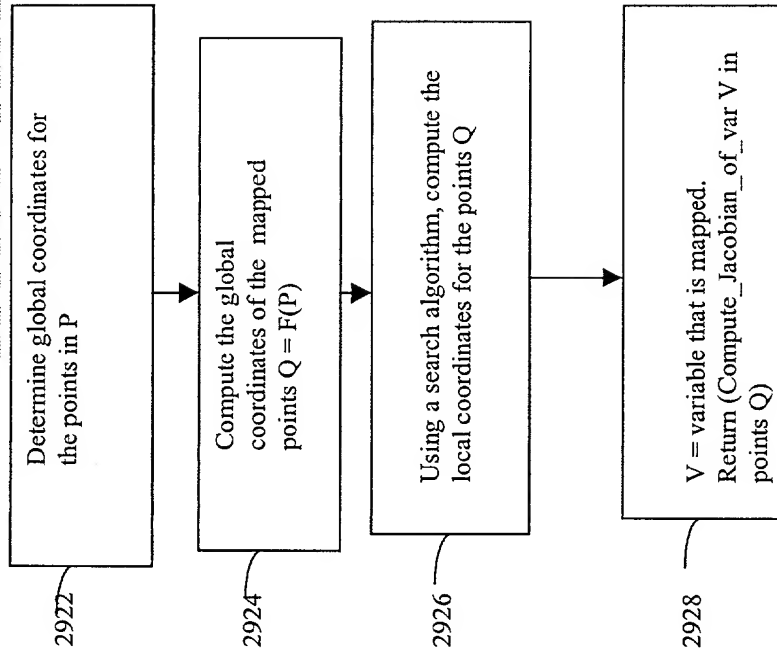


FIGURE 55L

Compute_Jacobian_of_integrated_var at a set of points P

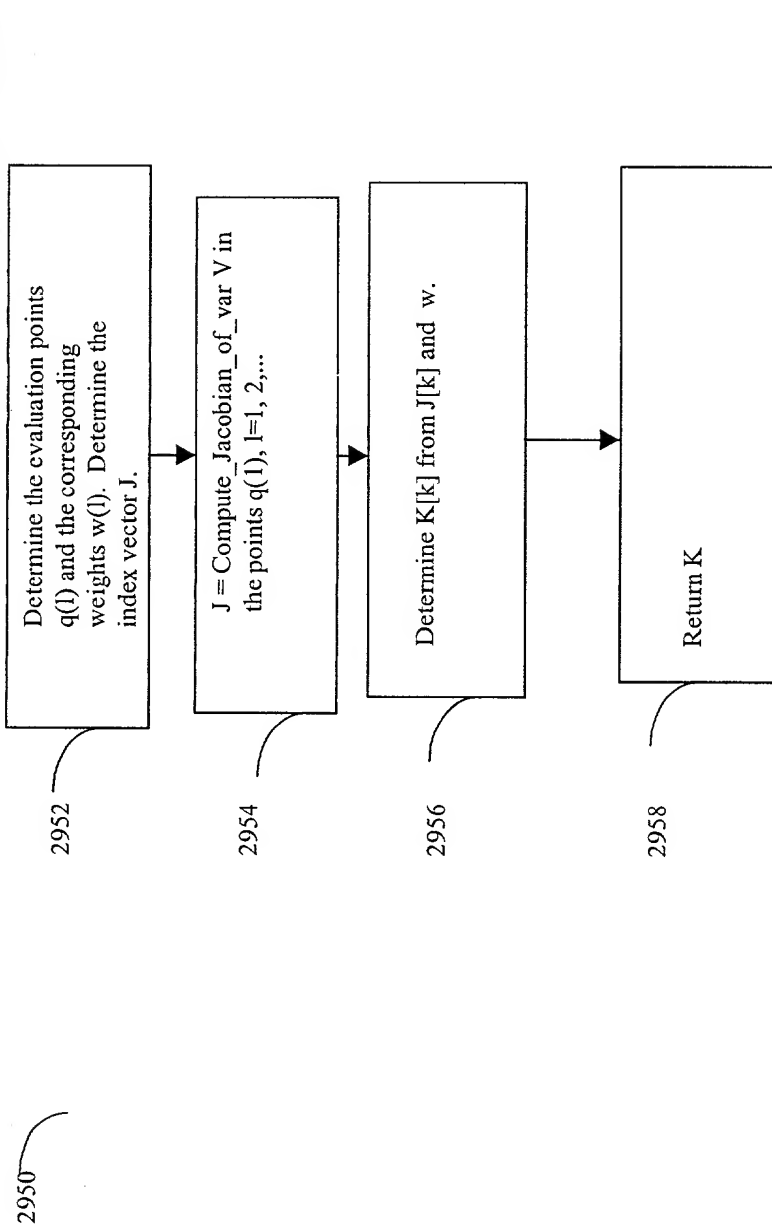


FIGURE 55M

FIG. 56 is a block diagram of a data structure 3000. The data structure 3000 is organized into a table with multiple rows and columns. The rows are labeled on the left side with reference numerals 3002, 3004a, 3004n, 3006, and 3016. The columns are labeled at the top with 'xmesh', 'fem[1]', ':', 'fem[g]', ':', 'elemcpl [1]', 'elemcpl [2]', and 'sol'. The data structure 3000 is further divided into sections 3004 and 3006. Section 3004 contains the rows 3002, 3004a, 3004n, and the first part of row 3006. Section 3006 contains the second part of row 3006 and row 3016. An arrow labeled 'xfem' points to the data structure 3000.

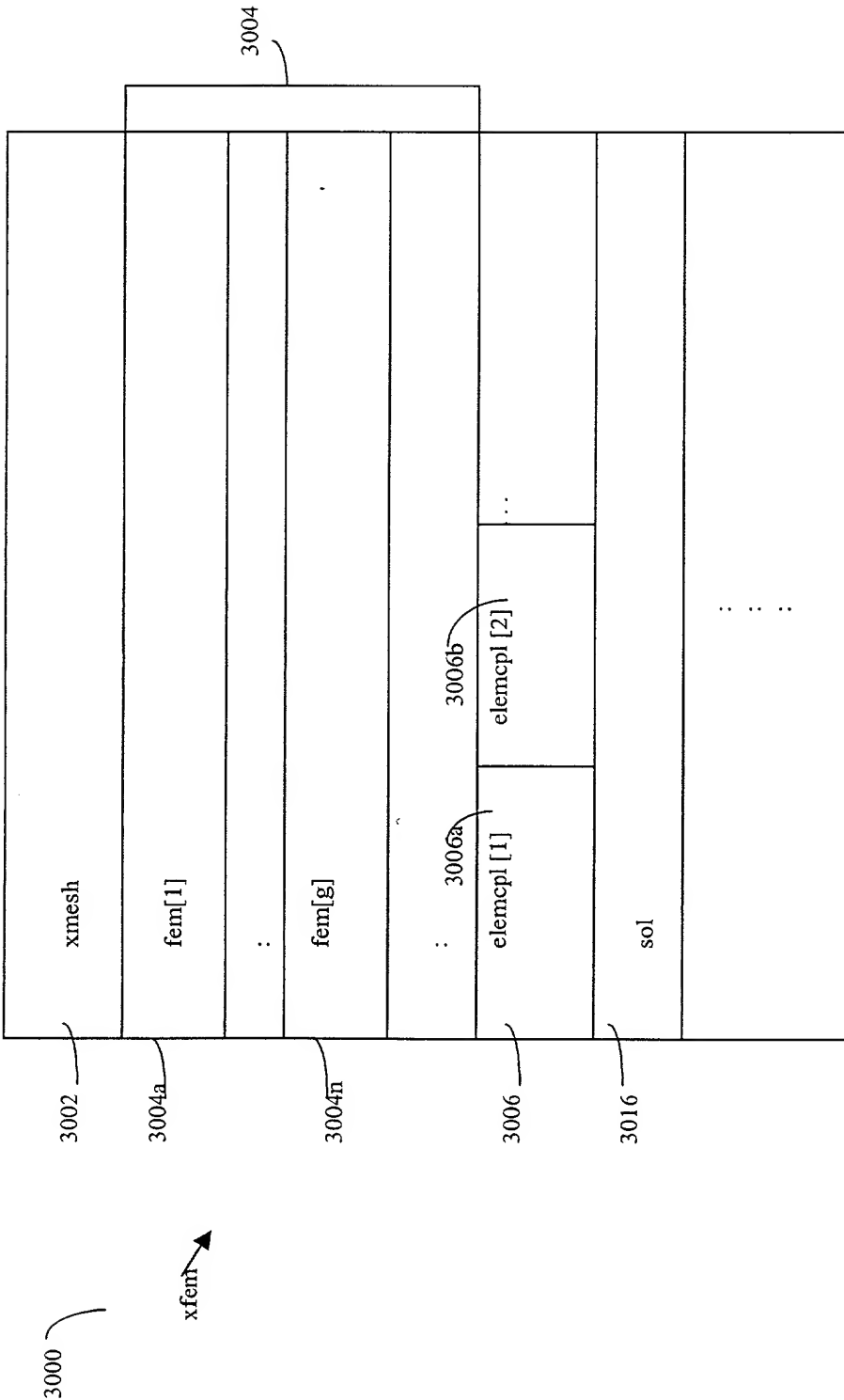


FIGURE 56

3006a

3020	elem {elcplscalar, elcplextr, elcplproj}									
3022	src									
	g	equ	bnd		edg		pnt		meshp	
		var	ind	var	ind	var	ind	var	ind	
3026	dst									
	g	equ	bnd		edg		pnt		ep	
		var	ind	var	ind	var	ind	var	ind	
	:									
	:									
	:									

FIGURE 57

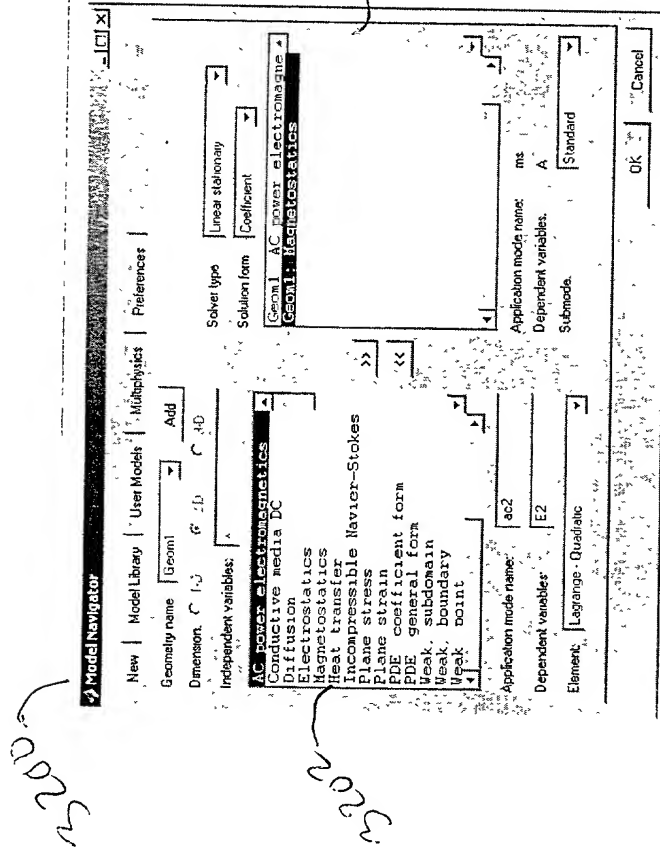


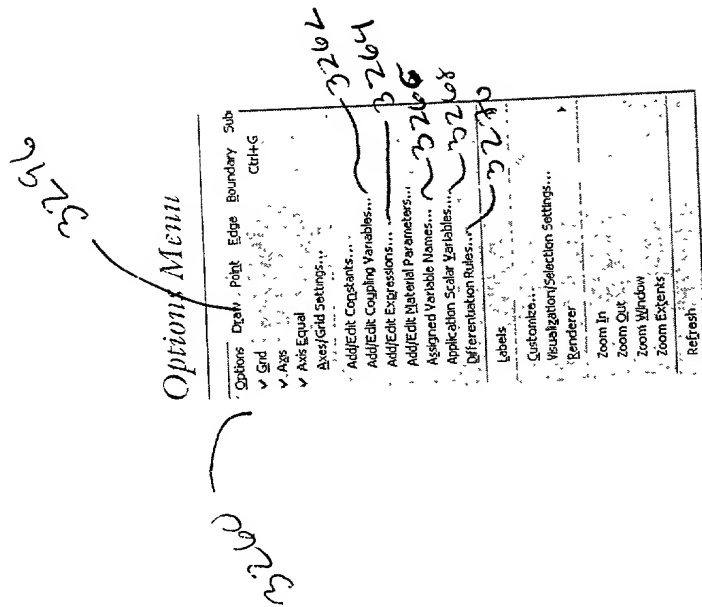
FIGURE 58

File Edit Options Draw Point Boundary Subdomain Mesh Solve Post
Ctrl+N Ctrl+S Ctrl+P Ctrl+V Ctrl+W

File Menu 3252
32254

File	Edit	Options	Draw	Point	Boundary	Subdomain	Mesh	Solve	Post
New...	Open								Ctrl+N
Save	Save As								Ctrl+S
Model Properties...									
Save Model Image									
Reset Model M-File...									
Import from Workspace									
Import from File									
Insert from Workspace									
Insert from File									
Import Properties...									
Export to Workspace									
Export to File									Ctrl+F
Export FEM Structure as Text									
Export Simulink Model...									
Export State-Space Model...									
Print...									
1 C:\MATLAB6p1\...Physics\hydrogen_atom.mat									
2 C:\MATLAB6p1\...MultiPhysics\micro_robot.mat									
3 C:\MATLAB6p1\...Equation_Based\designmodes_of_square.mat									
4 C:\MATLAB6p1\...Acoustics\humming_machinery.mat									
Exit									Ctrl+W

FIGURE 59



F1621620

ADD/EDIT EXPRESSIONS...
 2202 2202 2202

Expression Variable Settings

Variables	Definition	Type	Defined in
em s	subdomain	Geon1 Sub	Geon1 Sub
ve	geon1	Geon1	Geon1

Variable name: we
 Variable type: pomeity

Buttons: Add, Delete, On top, OK, Cancel, Apply

FIGURE 61

32nd ASSIGNED VARIABLE NAMES ...

Assigned Variables

Fixed name	Description	Assigned name
rho	space charge density	rho_es
px	polarization vector	px_es
py	polarization vector	py_es
pz	polarization vector	pz_es
Ex	electric field	Ex_es
Ey	electric field	Ey_es
Ez	electric field	Ez_es
Dx	electric displacement	Dx_es
Dy	electric displacement	Dy_es
Dz	electric displacement	Dz_es
nd	surface charge	nd_es

Assigned name for rho: rho_es

Set

FIGURE 62

APPLICATION SCALAR VARIABLES...

Assigned name	Description	Value
epsilon0_arp	permittivity	8.853335999999999e-012
mu0_arp	permeability	1.2566370614359172e-006
T_arp	time constant	1.0000000000000001e-017
omega_ac	angular frequency	314.15926535897933

OK Cancel Apply

Figure 63

DIFFERENTIATION RULES...

➤ Differentiation Rules

Function	Derivative
atanh	$1/(1-x^2)$
foo	$foo(x)/(1+foo(x)) / x$
bar	$3*bar(x) / x$

OK Cancel Apply

Name: bar

Derivative: 3*bar(x)/x

Set Delete

Figure 64

Point menu

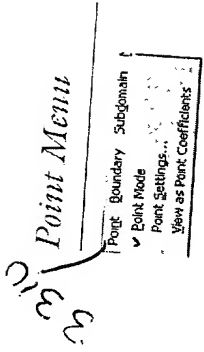


FIGURE 65

Point settings/Confident View

Init | Element | Weak

Domain selection

Initial value ☒ Units: 1

Variable	Value	Description
u0	1	Initial value

Name: 1

☐ Select by group

OK Cancel Apply

Figure 66

Edge Menu

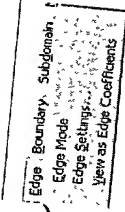


FIGURE 67

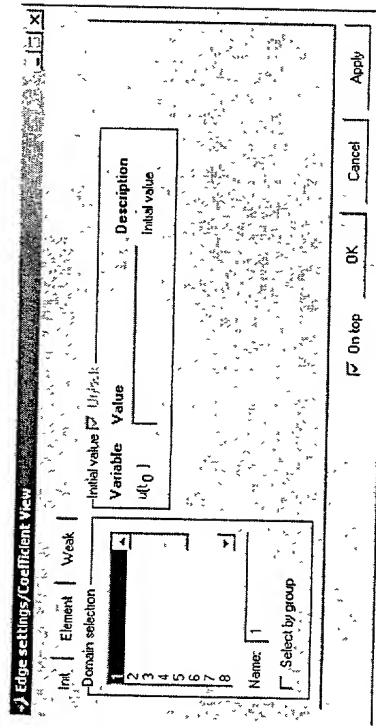


FIGURE 68

333301

1-D and 2-D

333320
333320
333320
333320

3-D

333320

Boundary	Subdomain	Mesh	Solve	Post
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
Boundary Mode				
<input checked="" type="checkbox"/> Boundary Settings...				
<input checked="" type="checkbox"/> Enable Borders				
<input checked="" type="checkbox"/> View as Boundary Coefficients				
<input checked="" type="checkbox"/> Show Direction Arrows				
<input checked="" type="checkbox"/> Generate Coupled Equation Variables				
<input checked="" type="checkbox"/> Generate Coupled Shape Variables				

FIGURE 69

$$\frac{\partial}{\partial t} \int_{\Omega} \rho u \, d\Omega + \int_{\partial \Omega} \rho u \, d\Gamma = 0$$

Boundary Settings/c1

Equation $n(\sigma(u, \nabla u)) + \rho u = g \cdot n$ in Ω , $u = 0$ on Γ_D

Coefficients | Weak

Domain selection

Weak complement ☒ Γ_D

Term	Value	Description
weak	0	Weak term
dweak	0	Time-dep. weak term
const	0	Constant

Name: 1

☐ Select by group

☐ Enable borders

On top OK Cancel Apply

336

Figure 70

3344

Boundary Settings/c1

Equation: $r(c7u-cou) = qu - g \cdot h \cdot hu = 1$

Type: ☐ q ☐ g ☐ h ☐ i ☐ Weak

Domain selection: ☐ 1 ☐ 2 ☐ 3 ☐ 4

Boundary condition type: ☒ Dirichlet ☐ Neumann

Name: 1

☐ Select by group ☐ Enable borders

On top ☒ Cancel Apply

FIGURE 71

Subdomain Settings/c1

Equation: $\nabla \cdot (c \nabla u) = \alpha u + \beta \nabla u = f$

Coefficients: ☐ Int ☐ Element ☐ Weak ☐ Weak complement ☒ Unsym

Domain selection: ☐ 1 ☒ 2

Term	Value	Description
weak	0	Weak term
dweak	0	Time-dep weak term
consti	0	Constraint

Name:

☐ Selected by group

☒ Active in the domain

☒ On top

Figure 7a

Solve Parameters				Solve				OK		Cancel		Apply	
General	Adaption	Nonlinear	Timestepping	Eigenvalue	Iterative	Multgrid	Multiphysics						
Solve type				Solution form									
<input checked="" type="checkbox"/> Stationary linear <input type="checkbox"/> Stationary nonlinear <input type="checkbox"/> Time dependent <input type="checkbox"/> Eigenvalue				<input type="checkbox"/> Coefficient <input type="checkbox"/> Automatic differentiation <input type="checkbox"/> $\frac{\partial \psi}{\partial t}$ <input type="checkbox"/> $\frac{\partial \psi}{\partial x}$ <input type="checkbox"/> $\frac{\partial \psi}{\partial y}$ <input type="checkbox"/> $\frac{\partial \psi}{\partial z}$ <input checked="" type="checkbox"/> Streamline diffusion <input type="checkbox"/> $\frac{\partial \psi}{\partial t}$ <input checked="" type="checkbox"/> Simplify									
<input checked="" type="checkbox"/> Print report				<input type="checkbox"/> Steady state diffusion <input type="checkbox"/> $\frac{\partial \psi}{\partial t}$									
Advanced				Geometry shape order				Assembly block size					
<input type="checkbox"/> Coefficient handling method <input type="checkbox"/> Elimination				<input type="checkbox"/> Automatic <input type="checkbox"/> Null spaces function <input type="checkbox"/> Orthogonal (rankfullth)				<input type="checkbox"/> Context <input type="checkbox"/> Local workspace					
<input type="checkbox"/> Fixed point iteration <input type="checkbox"/> Direct linear solver				<input type="checkbox"/> Jacobian <input type="checkbox"/> Mailbox				<input type="checkbox"/> Fixed point iteration <input type="checkbox"/> Direct linear solver					

F1622E 73

Solver Parameters

General | Adaption | Nonlinear | Timestopping | Eigenvalue | Iterative | Multigrid | Multiphysics

☐ Show variables

Geom1: 2 variable coefficient form PDE (G1)

Update mechanism for initial value u

Store Solution ☐ Store solution automatically ☐ Use solution number 1

Solve OK Cancel Apply

F16eure 74

Multiphysics Window: Help
 Add/Edit Modes...
 Solve for Variables...

1 Geom1: 2 variable coefficient form PDE (ci)
 2 Geom1: Conductive Media DC (dc)
 3 Geom2: Electrostatics (es)

33901

ADD/EDIT MODES ...

Model Navigator

Geom1 | Geom2 | Add

Dimension: 1, 2, 3D

Independent variables:

Conductive media DC
 Diffusion
 Electrostatics
 Magnetostatics
 Heat transfer
 Incompressible Navier-Stokes
 Structural mechanics
 PDE, coefficient form
 PDE, general form
 Weak, boundary
 Weak, edge
 Weak, point
 Weak, boundary constraint

Solver type: Linear stationary

Solution form: Coefficient

Geom1: PDE, coefficient form
 Geom2: Conductive media DC
 Geom3: Electrostatics
 Geom4: Structural mechanics

Application mode name: dc2

Dependent variables: V3

Element: Lagrange, Quadratic

Application mode name: sm

Dependent variables: u2, v2, w2

Submode: Standard

OK Cancel

Figure 75